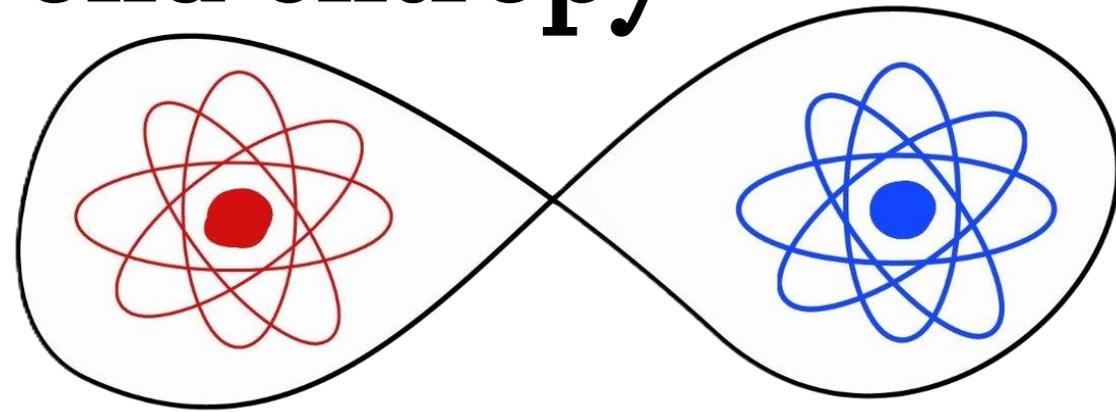


Thermodynamic signatures of Gaussian entanglement beyond entropy

Bea Polo, Federico Centrone,
Alimuddin Mir & Gerardo Adesso



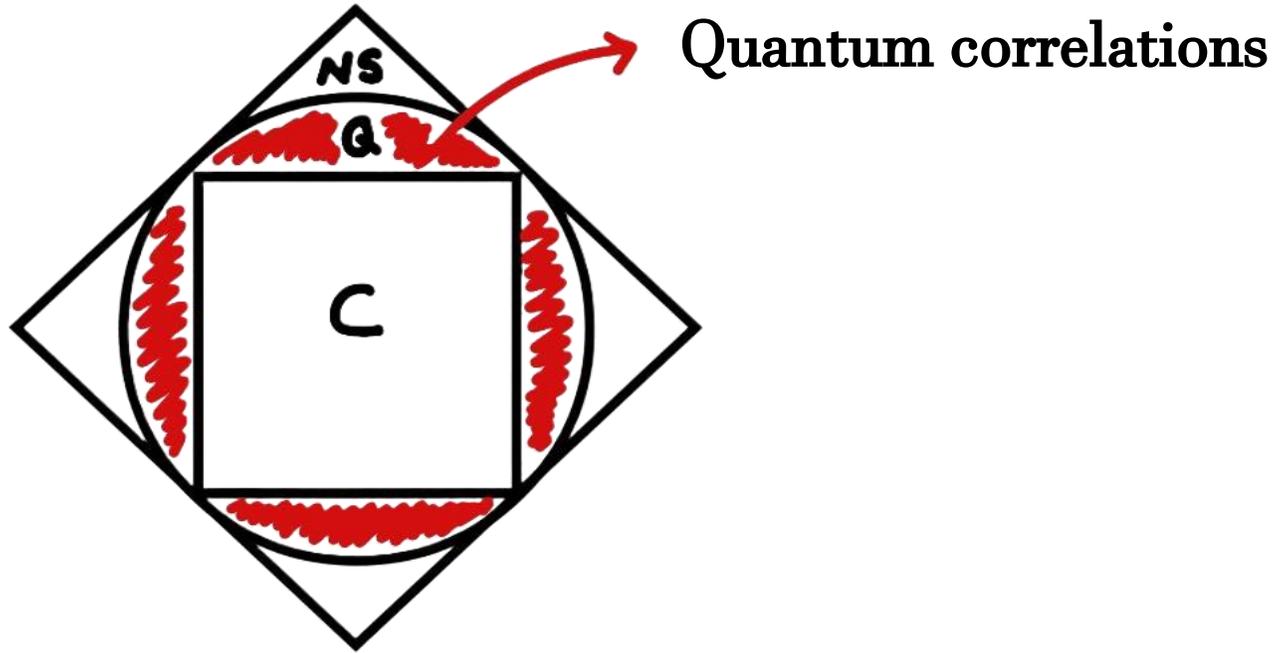
ArXiv preprint:



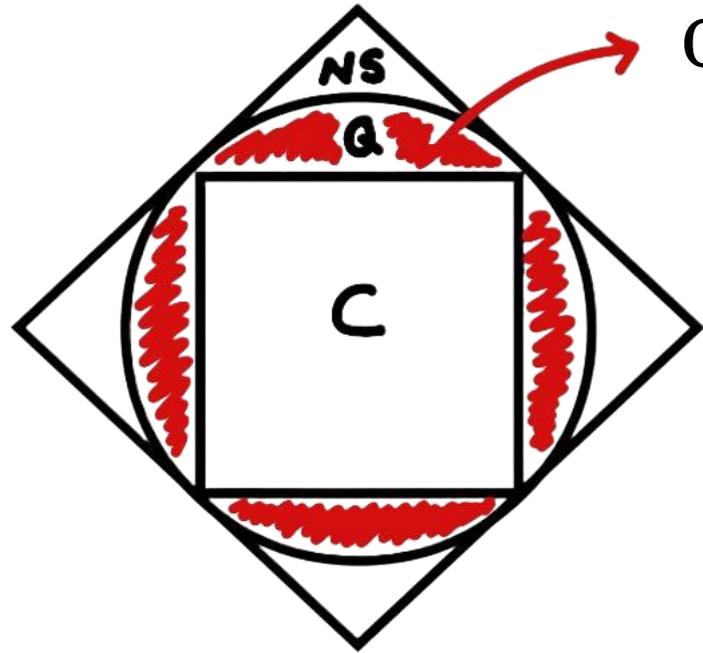
International Conference on Quantum Energy
Padova, 3rd June 2025

ICFO^R

1. INTRODUCTION



1. INTRODUCTION



Quantum correlations



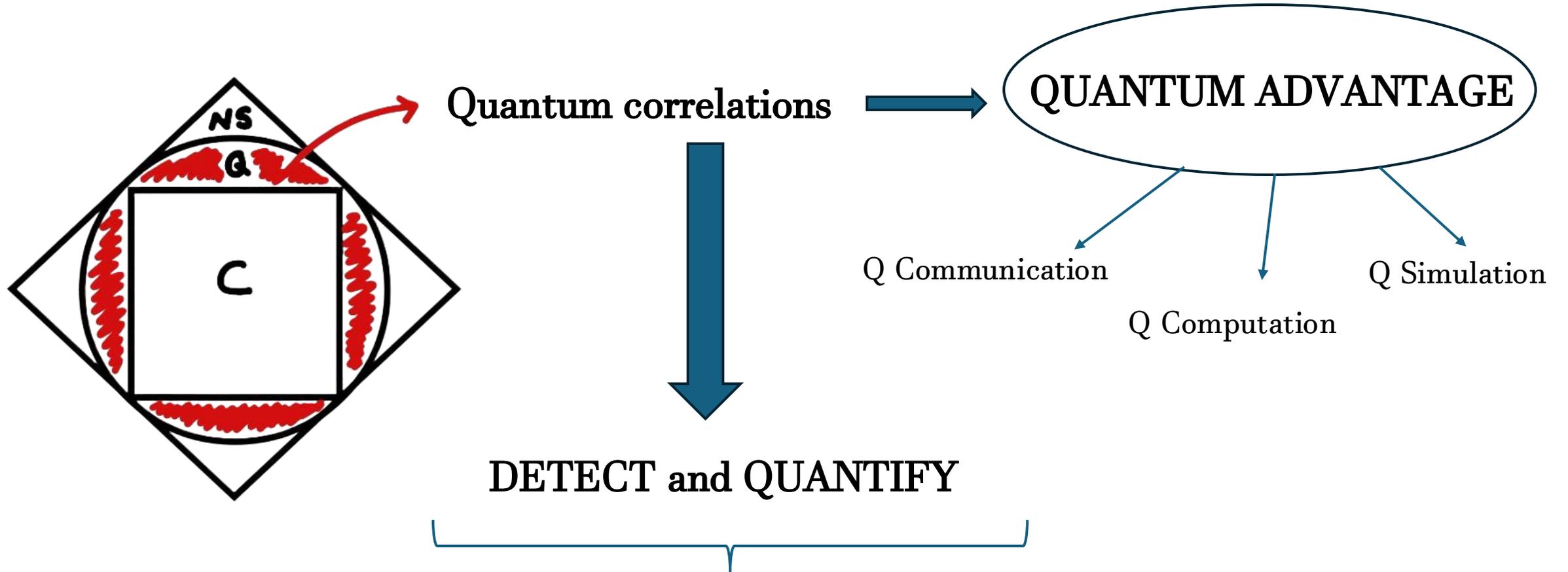
QUANTUM ADVANTAGE

Q Communication

Q Computation

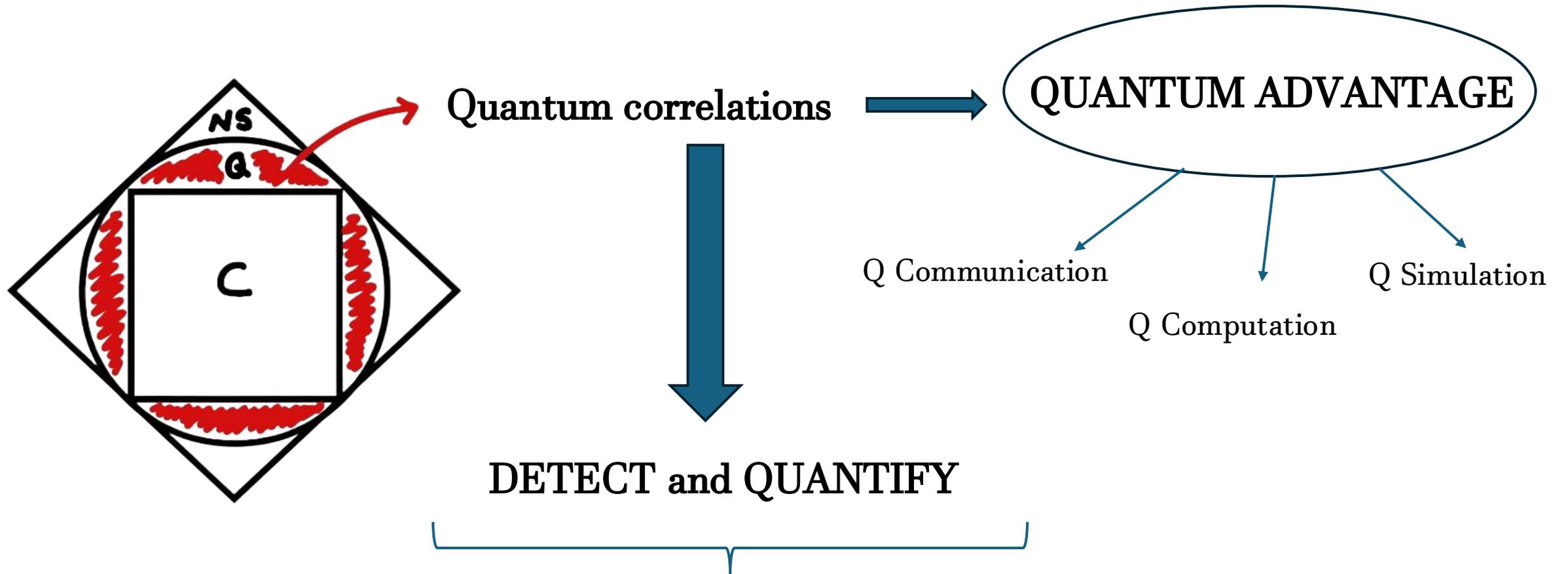
Q Simulation

1. INTRODUCTION



Mutual information, conditional entropy, accessible information...

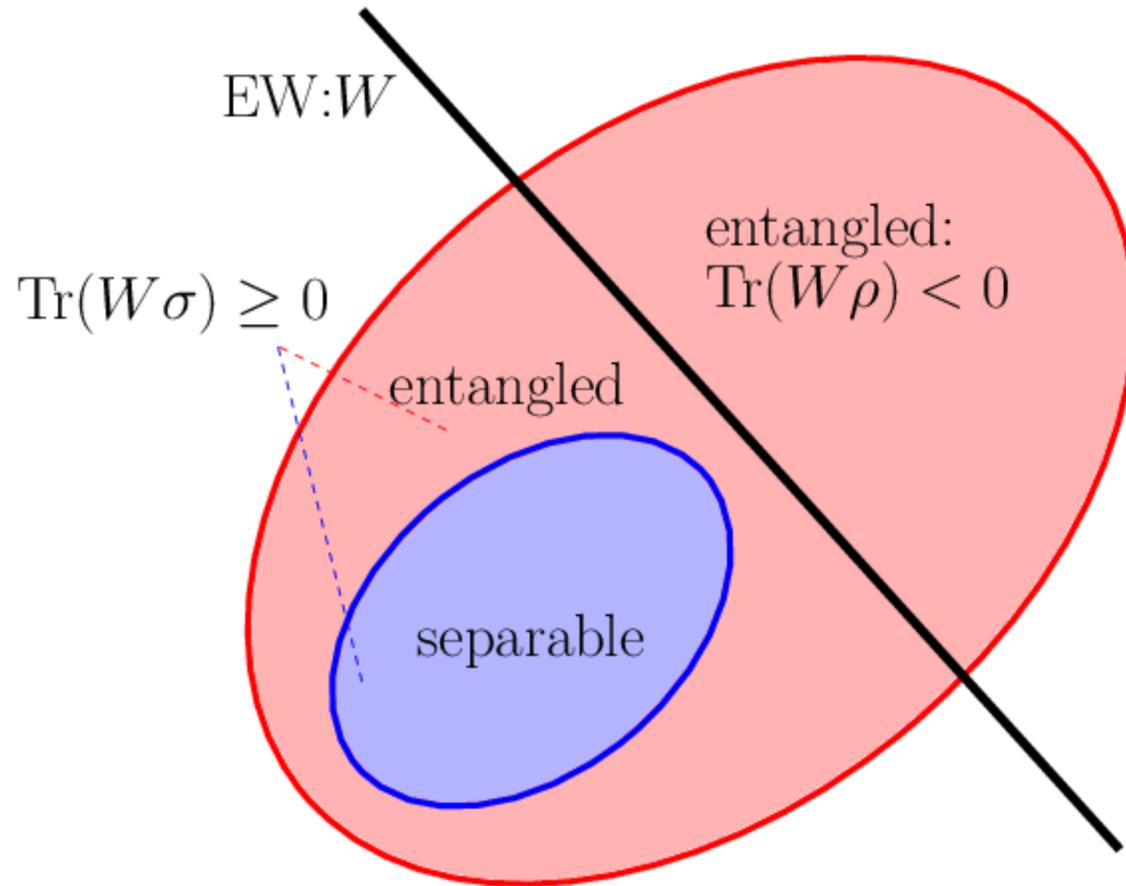
1. INTRODUCTION



Mutual information, conditional entropy, accessible information... require full tomography!! (resource expensive)

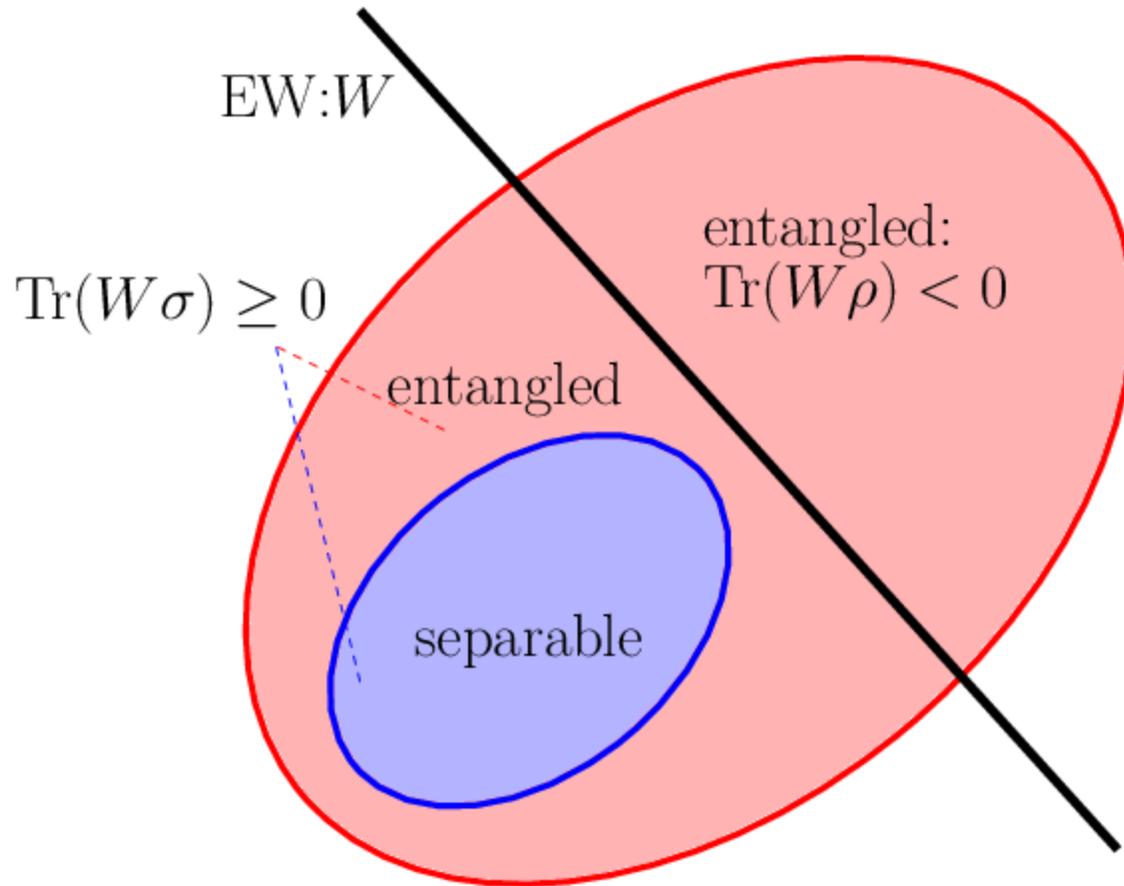
1. INTRODUCTION

Entanglement witnesses



1. INTRODUCTION

Entanglement witnesses



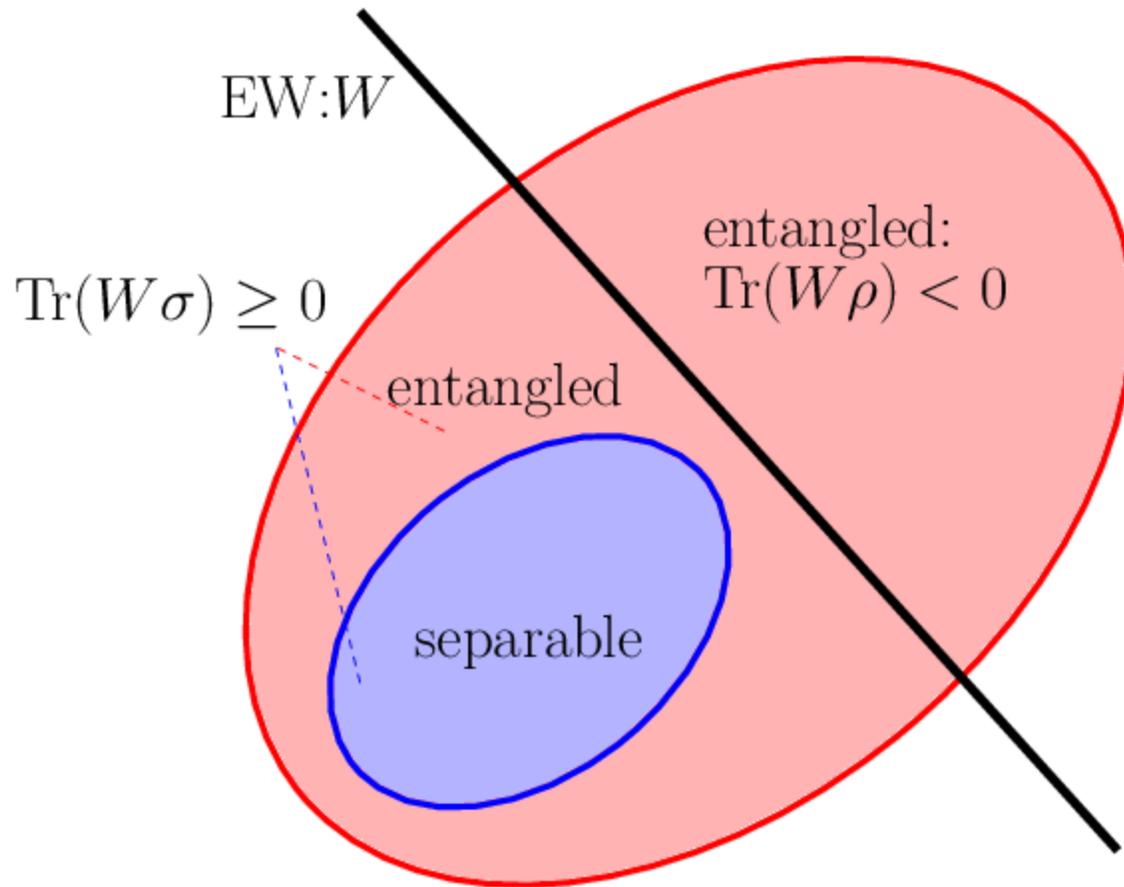
NOT necessary **BUT** sufficient

certification of the presence of
entanglement in the measured state

W ??

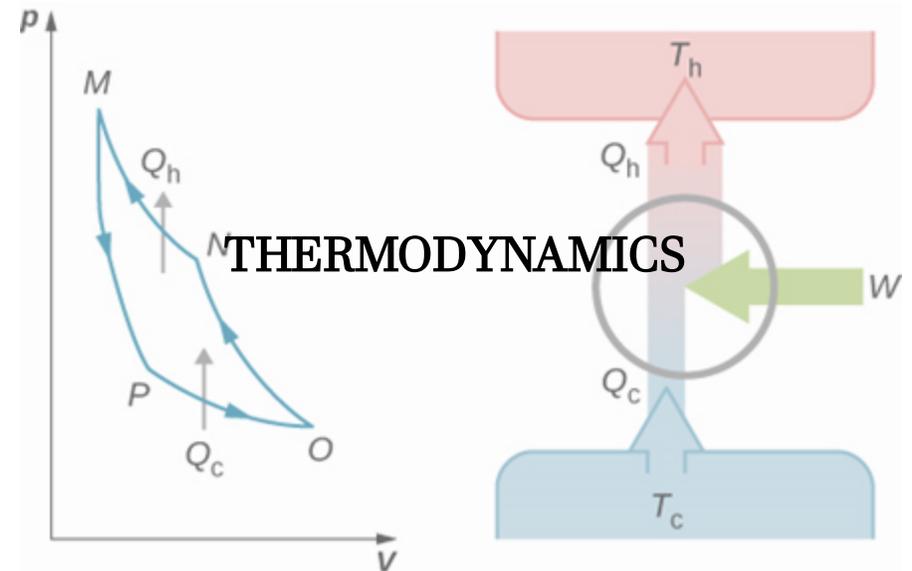
1. INTRODUCTION

Entanglement witnesses

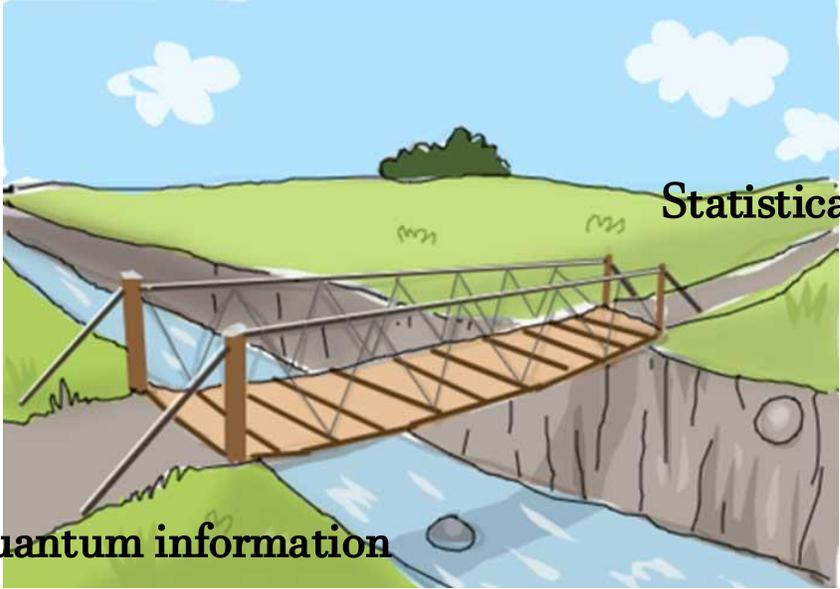


NOT necessary **BUT** sufficient

certification of the presence of entanglement in the measured state



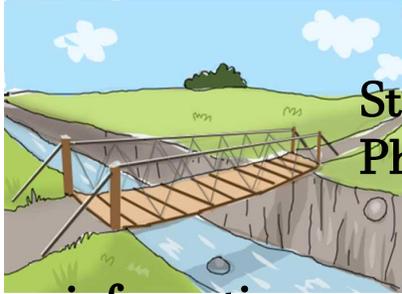
1. INTRODUCTION



Statistical Physics

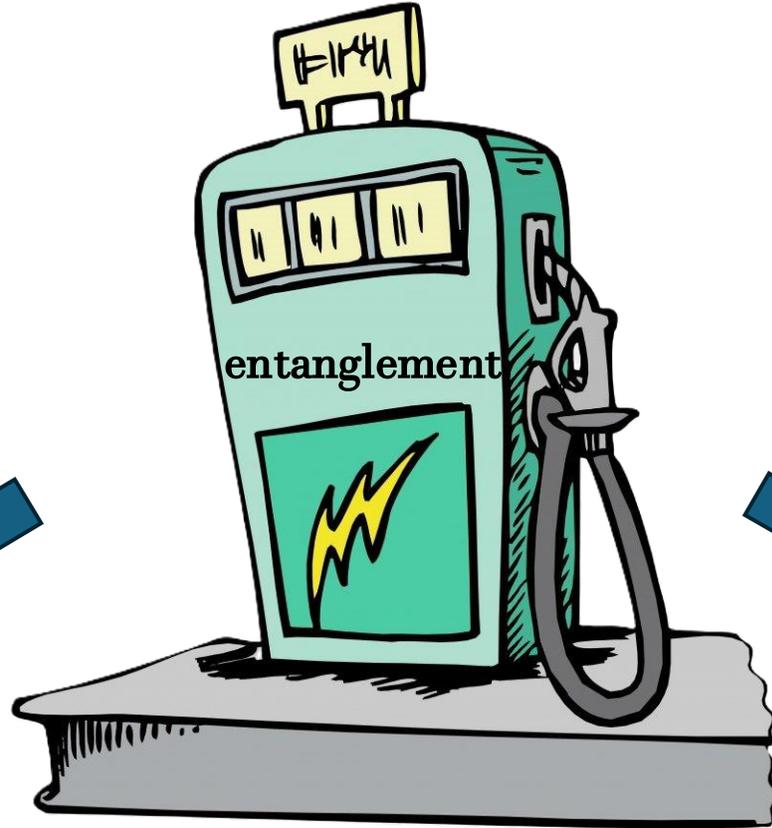
Quantum information

1. INTRODUCTION



Statistical
Physics

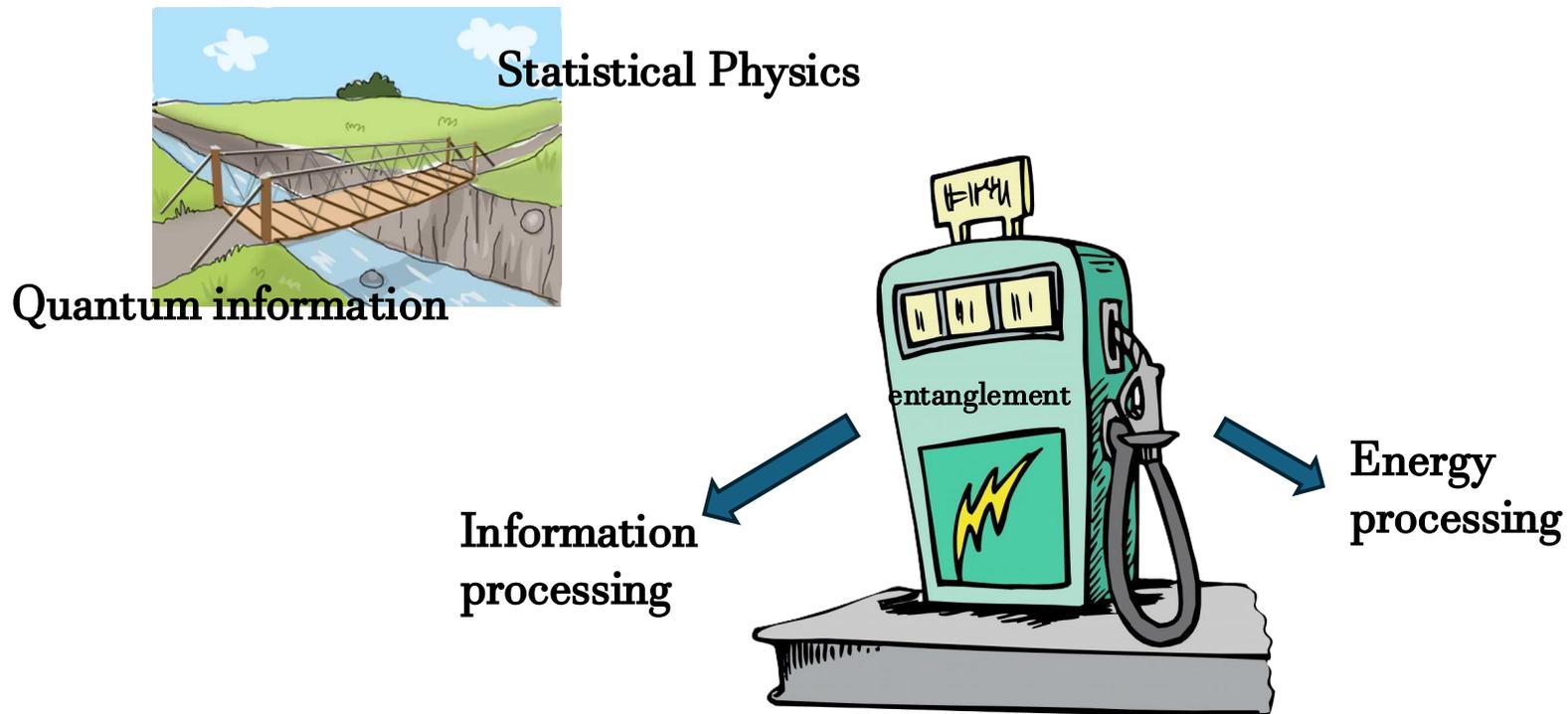
Quantum information



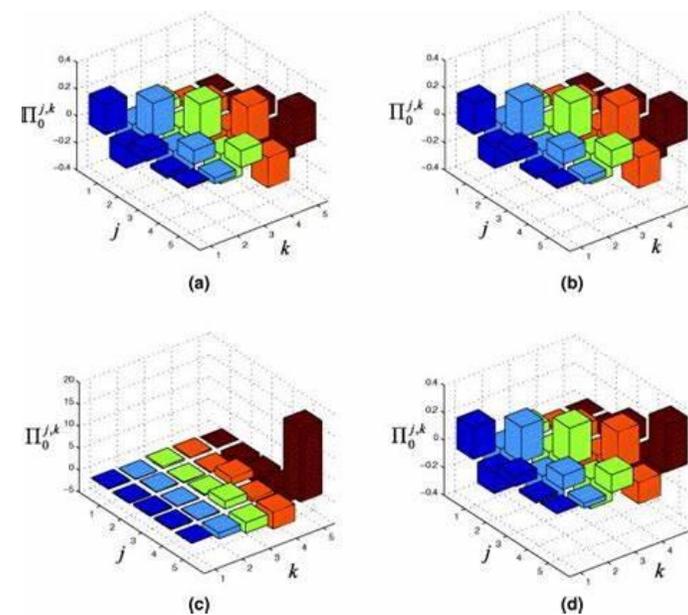
Information processing

Energy processing

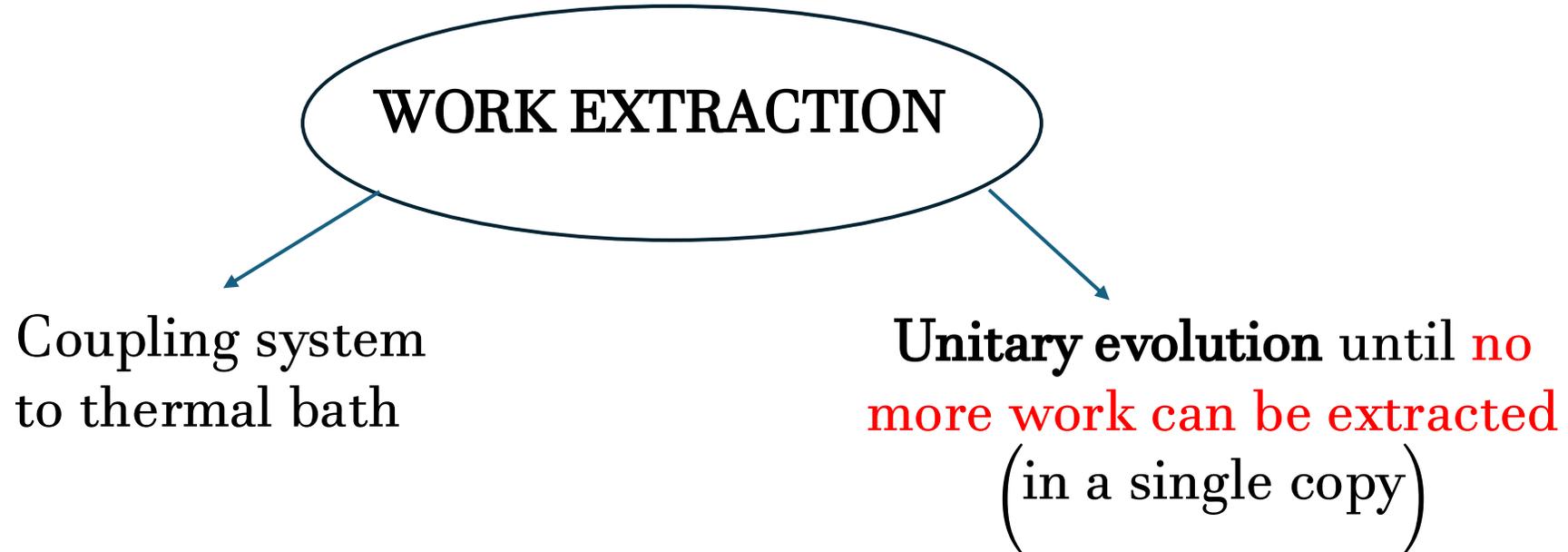
1. INTRODUCTION



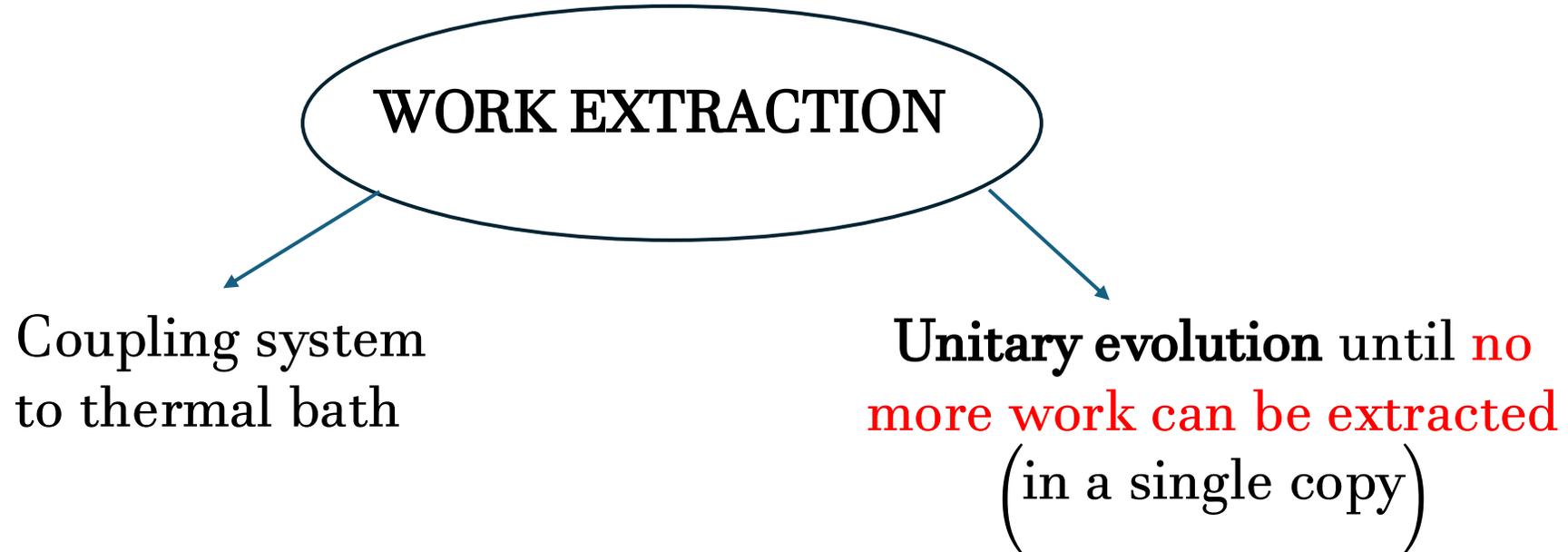
Less number of copies as compared to tomography?



1. INTRODUCTION



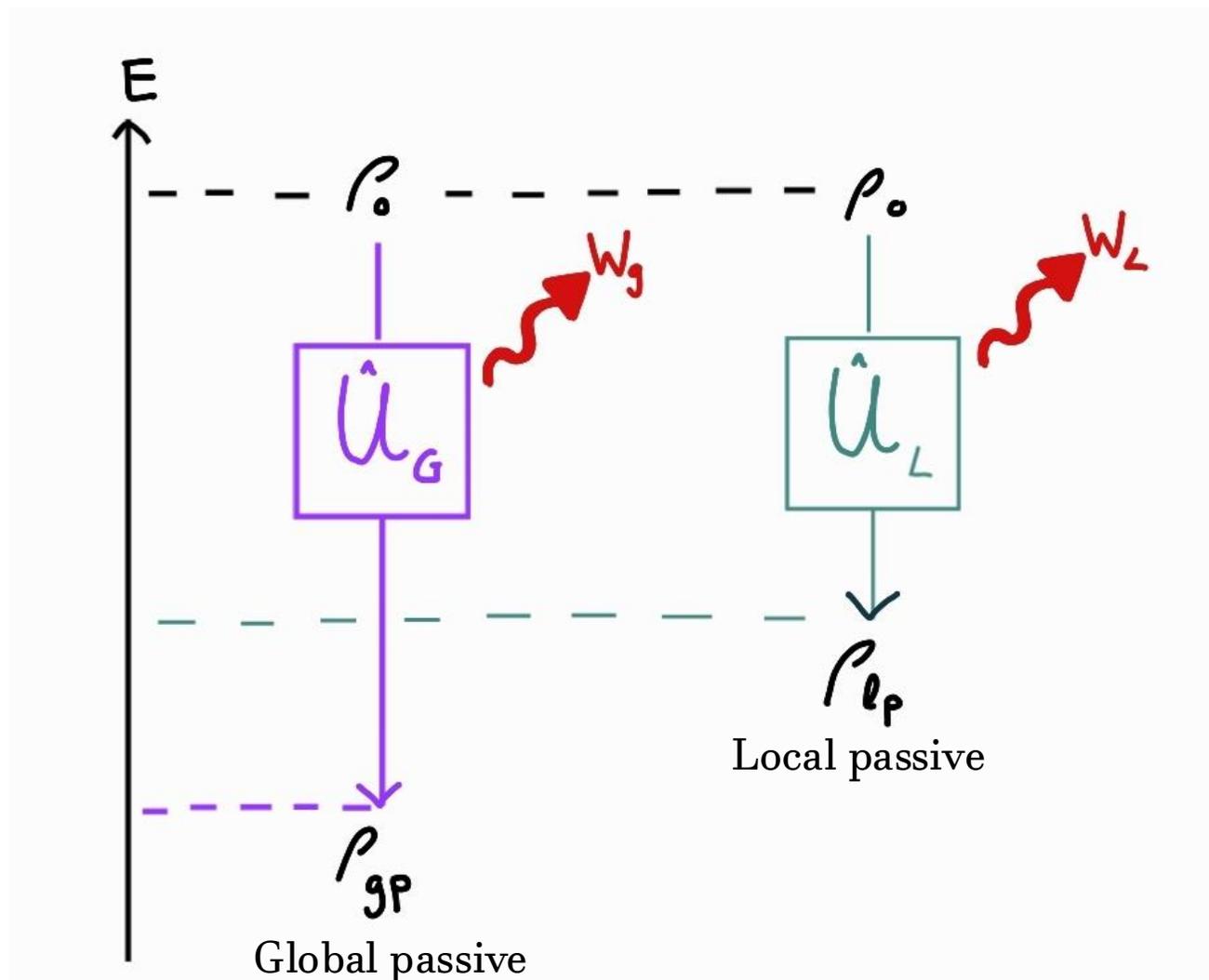
1. INTRODUCTION



$$\rho_0 \rightarrow \boxed{\hat{U} = e^{-i\hbar \int_0^\tau dt H+V(t)}} \rightarrow \underbrace{\rho' = \hat{U}^\dagger \rho_0 \hat{U}}_{\text{passive state}}$$

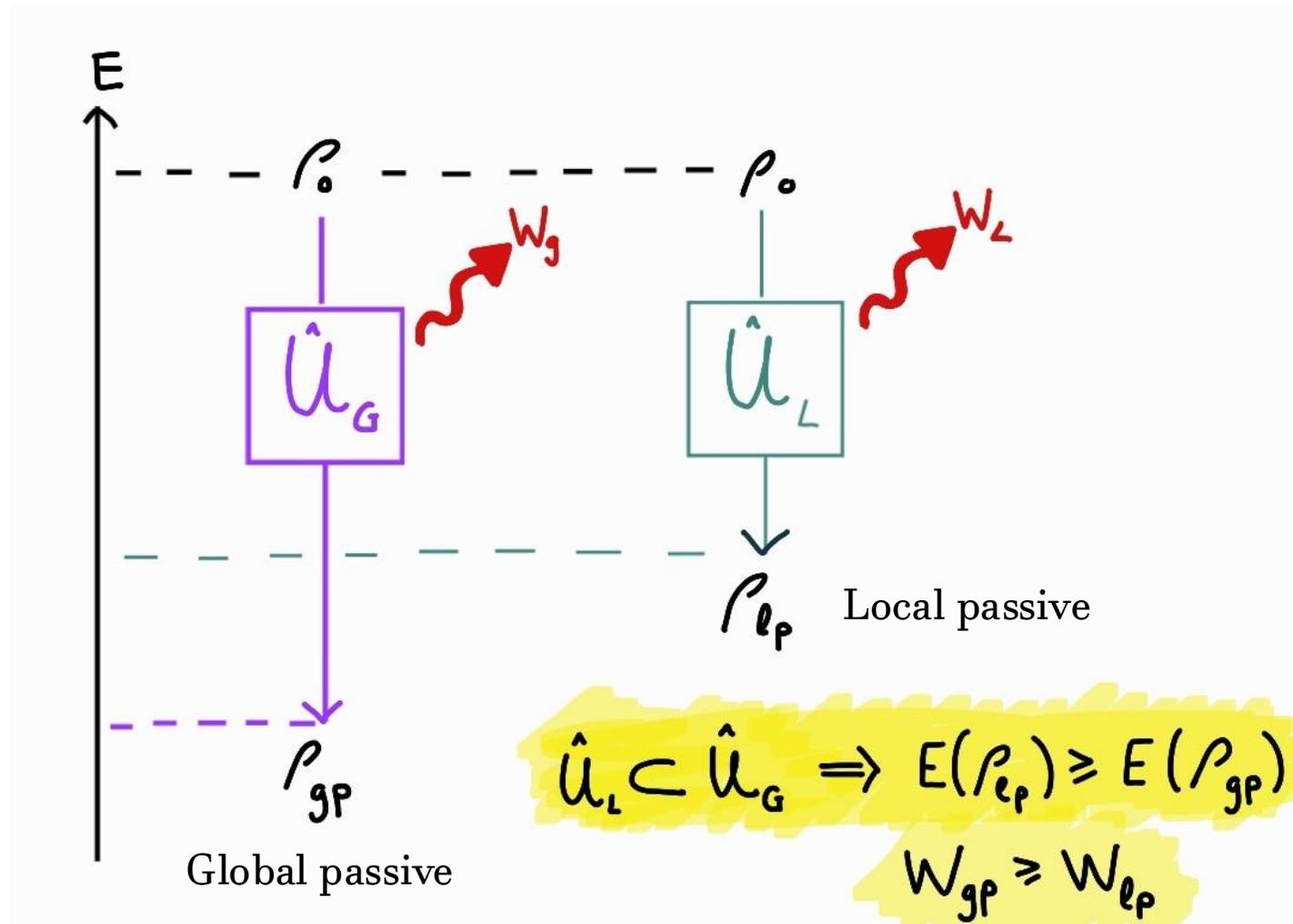
1. INTRODUCTION

2 types of passivity:



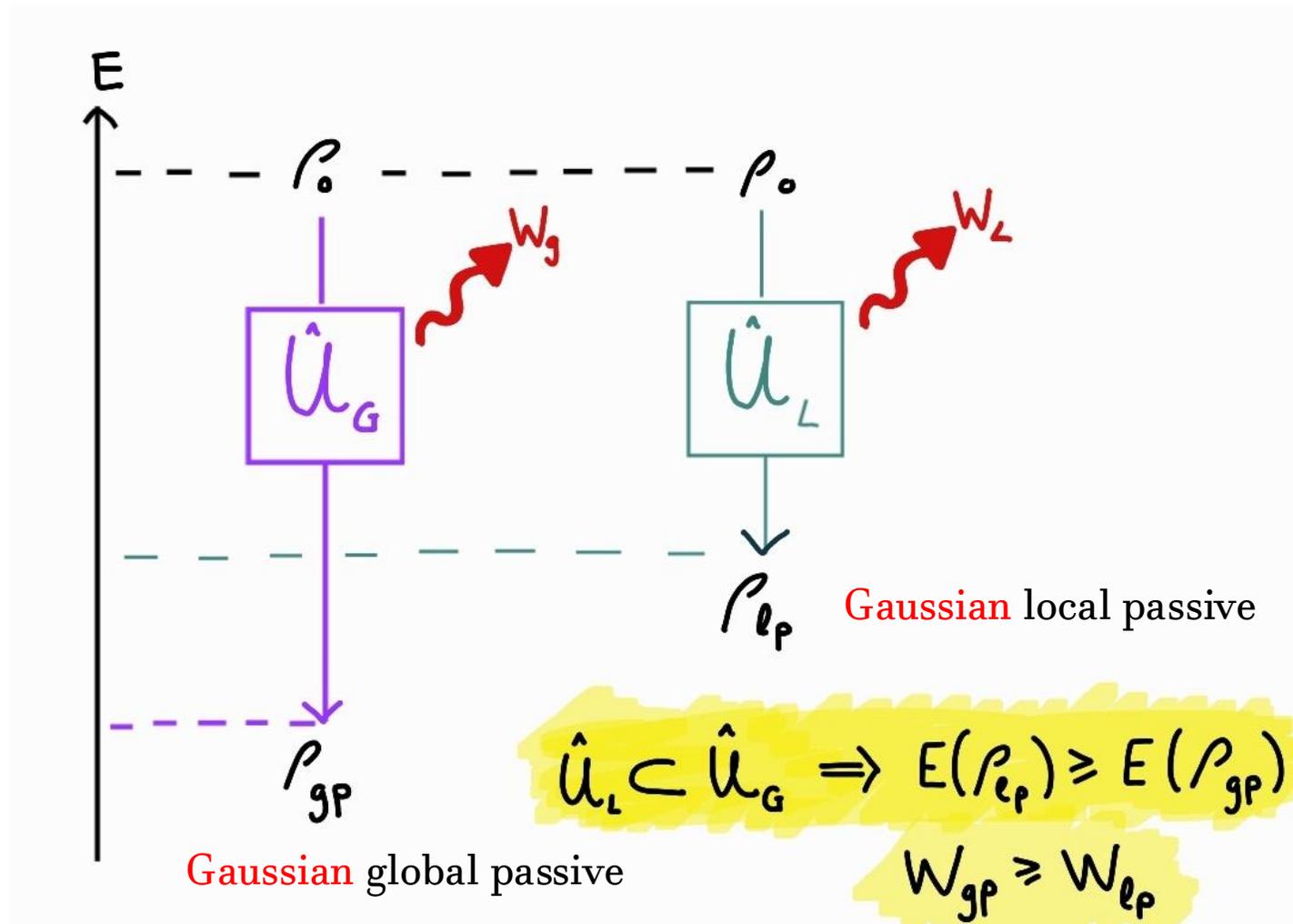
1. INTRODUCTION

2 types of passivity:



1. INTRODUCTION

2 types of passivity:



2. ERGOTROPIC GAP as ENTANGLEMENT WITNESS

$$\Delta\mathcal{E} = E_{\text{loc p}} - E_{\text{glob p}}$$



Entanglement

2. ERGOTROPIC GAP as ENTANGLEMENT WITNESS

$$\Delta\mathcal{E} = E_{\text{loc } p} - E_{\text{glob } p}$$



Entanglement

Bound on ergotropic gap for bipartite separable states

[Mir Alimuddin*](#), [Tamal Guha†](#), and [Preeti Parashar‡](#)

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Phys. Rev. A **99**, 052320 – Published 14 May, 2019

DOI: <https://doi.org/10.1103/PhysRevA.99.052320>

Valid entanglement measure *for pure bipartite states in DV framework*

- Zero for product states
- Non-zero for all entangled states
- Monotonically decreasing under LOCC

2. ERGOTROPIC GAP as ENTANGLEMENT WITNESS

$$\Delta\mathcal{E} = E_{\text{loc } p} - E_{\text{glob } p}$$



Entanglement

Not an entanglement monotone
for mixed states



Bound on ergotropic gap
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Bound on ergotropic gap for bipartite separable states

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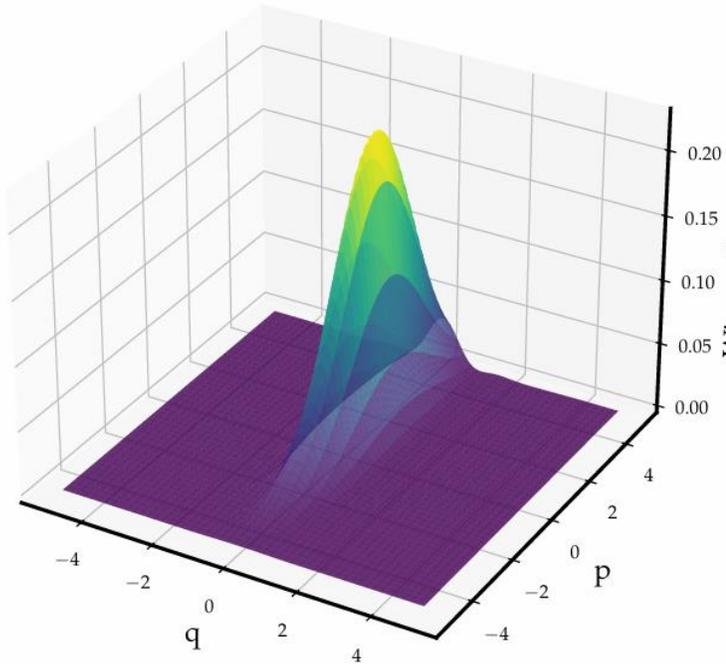
Not an entanglement monotone
for mixed states



Bound on ergotropic gap
for mixed separable states

Extension to Continuous Variables???

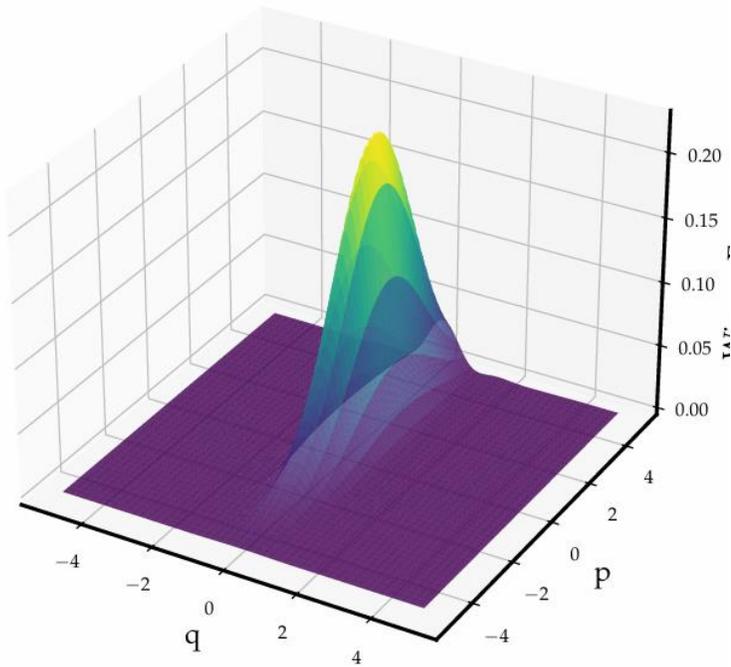
Gaussian case



- Easily-tractable subset of continuous-variable states (few parameters needed for their characterization)
- Two-mode Gaussian study \longrightarrow generalizable to any bipartite Gaussian if certain symmetries are present (locally symmetric).
- Parametrization (Bloch-Messiah):

temperature factors	squeezing	beam-splitter angle	frequencies
$k_1, k_2 \longrightarrow \begin{cases} k = \frac{k_1 + k_2}{2} \\ \gamma = \frac{k_1 - k_2}{2} \end{cases}$	z_1, z_2	θ	$\omega_1, \omega_2 \longrightarrow \begin{cases} \omega = \omega_1 \\ \alpha = \frac{\omega_2}{\omega_1} \end{cases}$

Gaussian case



- Easily-tractable subset of continuous-variable states (few parameters needed for their characterization)
- Two-mode Gaussian study \longrightarrow generalizable to any bipartite Gaussian if certain symmetries are present.
- Bloch-Messiah parametrization

$$\Delta\mathcal{E}_{\rho_G} \rightarrow \Delta\mathcal{E}_{\rho_G}(k, \gamma, z_1, z_2, \alpha, \theta)$$

- But results are **independent of the parametrization choice**

3. RESULTS

3. RESULTS

Pure case $k = 1, \gamma = 0$

- Analogous to DV case
- $\Delta\epsilon$ is a valid measure of entanglement
- $\Delta\epsilon$ is functionally dependent on mutual information

3. RESULTS

Mixed case

Unlike DV, $\Delta\mathcal{E}$ is nonzero if and only if there exist correlations
between the two modes



3. RESULTS

Mixed case

First observation: $\Delta\epsilon$ grows with temperature in CV systems !!



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Counter intuitive: correlations should decrease with more noise destroying coherence

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Mixed case

First observation: $\Delta\epsilon$ grows with temperature in CV systems !!



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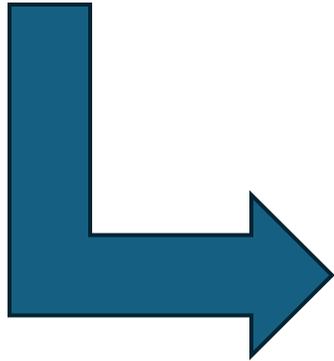
Consider relative ergotropic gap instead of absolute one:

$$\Delta\mathcal{E}_{rel} = \frac{E_{loc \text{ passive}} - E_{glob \text{ passive}}}{E_{glob \text{ passive}}} \quad \text{for } E_{glob \text{ passive}} \neq 0$$

3. RESULTS

Mixed case

$$\Delta \mathcal{E}_{rel} = \frac{E_{loc \text{ passive}} - E_{glob \text{ passive}}}{E_{glob \text{ passive}}} \quad \text{for } E_{glob \text{ passive}} \neq 0$$



Functionally independent of mutual information!!!

3. RESULTS

Mixed case

$$\Delta\mathcal{E}_{rel} \leq B \text{ for } \rho \text{ separable}$$

???

3. RESULTS

Mixed case


$$\Delta\epsilon_{rel} \leq B$$

for ρ separable

Impose PPT-based
separability condition for
Gaussian states

3. RESULTS

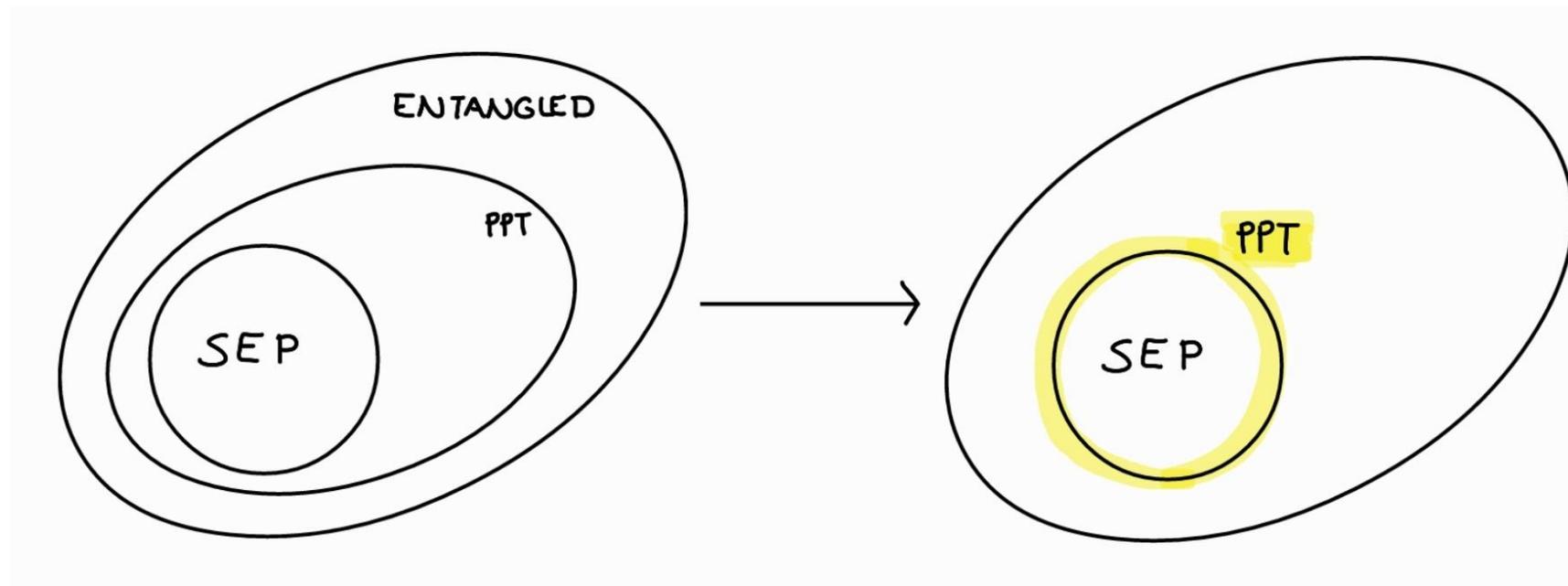
Mixed case

$$\Delta\mathcal{E}_{rel} \leq B^{\text{sep}} \quad \rho \text{ separable}$$



$$B^{\text{sep}} \rightarrow B^{\text{sep}}(k, \gamma, \alpha)$$

Since PPT is **necessary**
AND sufficient for
separability of two-
mode Gaussian states...



Since PPT is **necessary**
AND sufficient for
separability of two-
mode Gaussian states...

$$\Delta\mathcal{E}_{rel} \geq B^{\text{ent}} \quad \rho \text{ entangled}$$

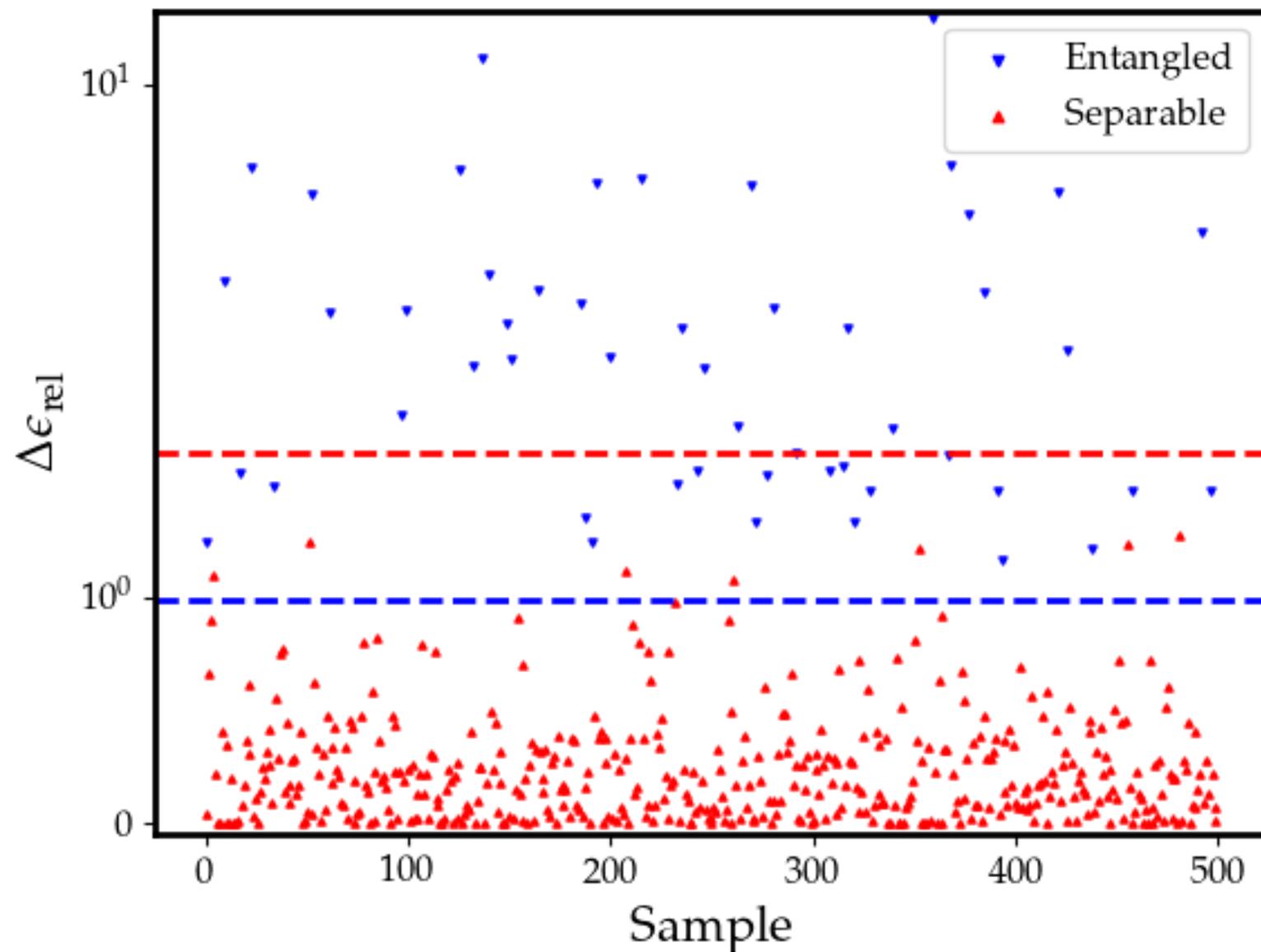
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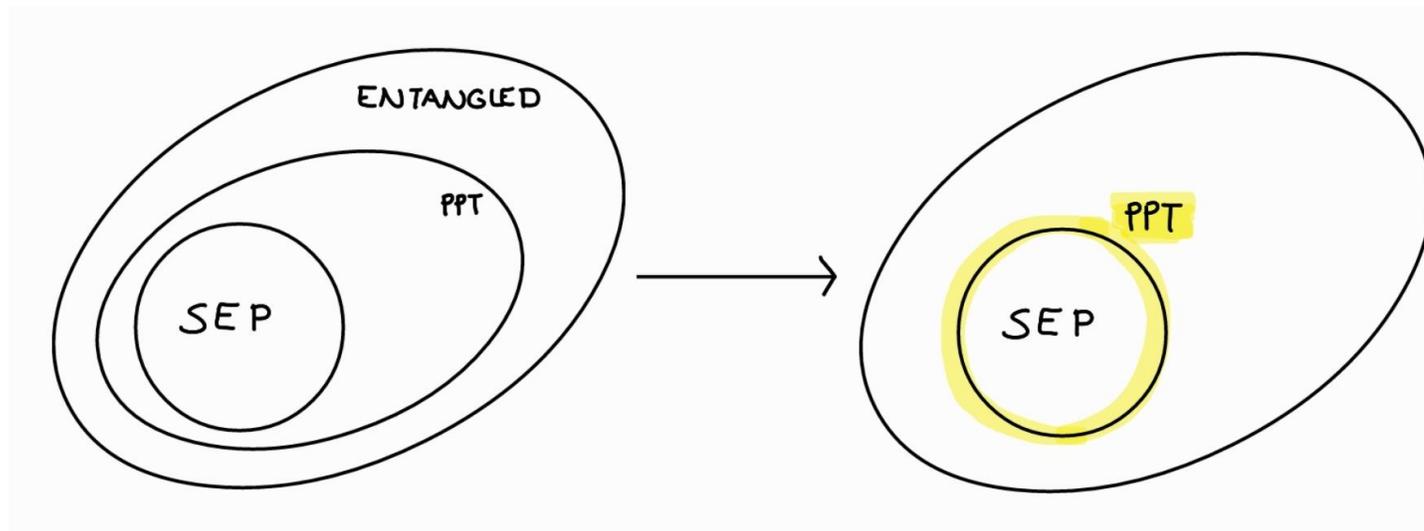
$$B^{\text{ent}} \rightarrow B^{\text{ent}}(k, \gamma, \alpha)$$

3. RESULTS



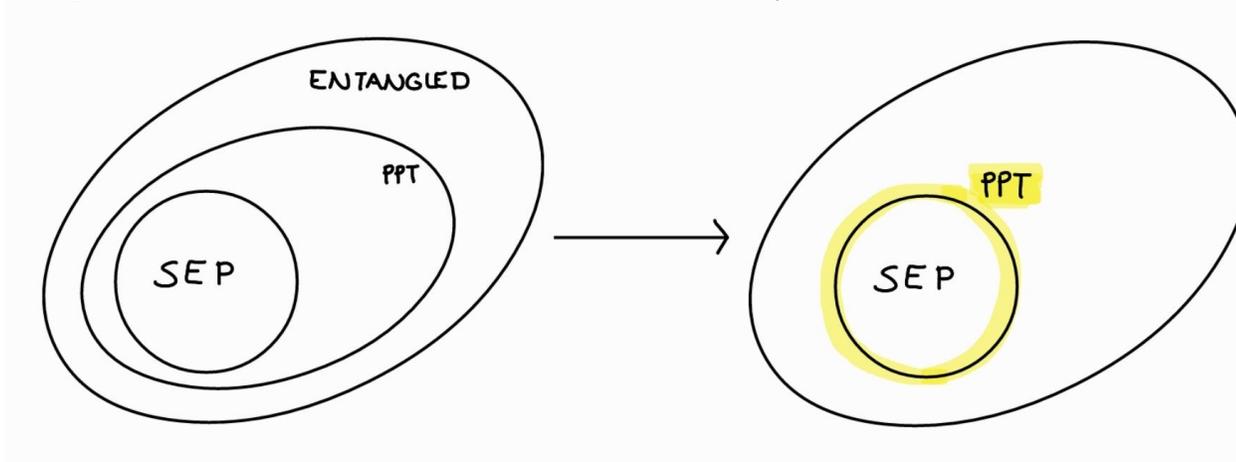
3. RESULTS

For locally symmetric bipartite Gaussians, PPT is necessary and sufficient:

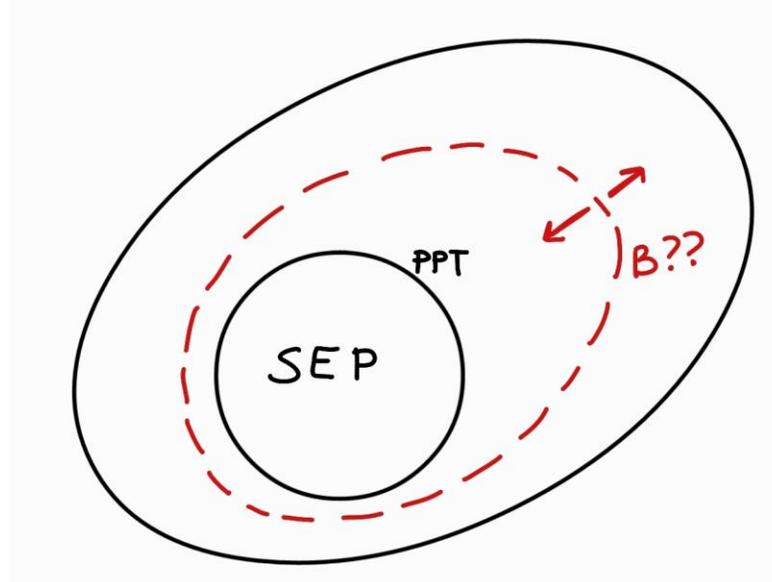


3. RESULTS

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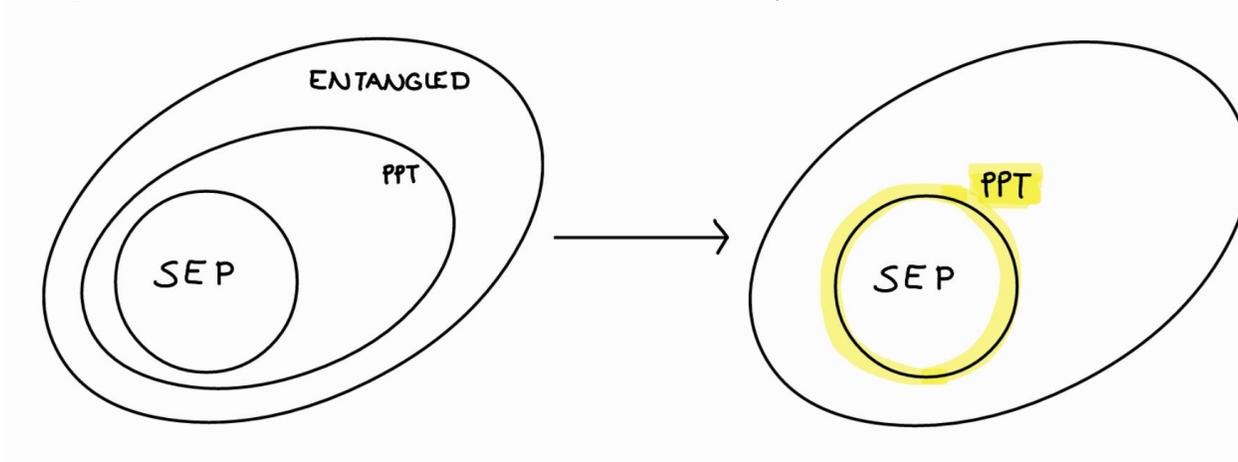


Question: how “good” is our criterion at detecting entangled states?

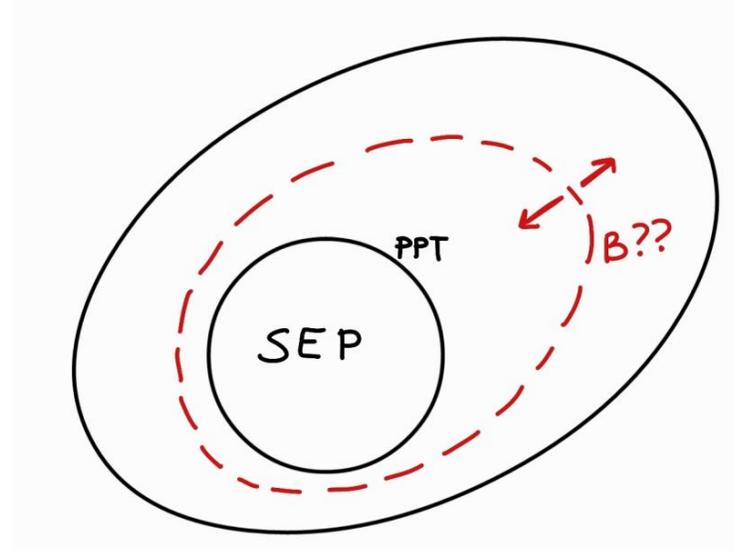


3. RESULTS

For locally symmetric bipartite Gaussians, PPT is necessary and sufficient:



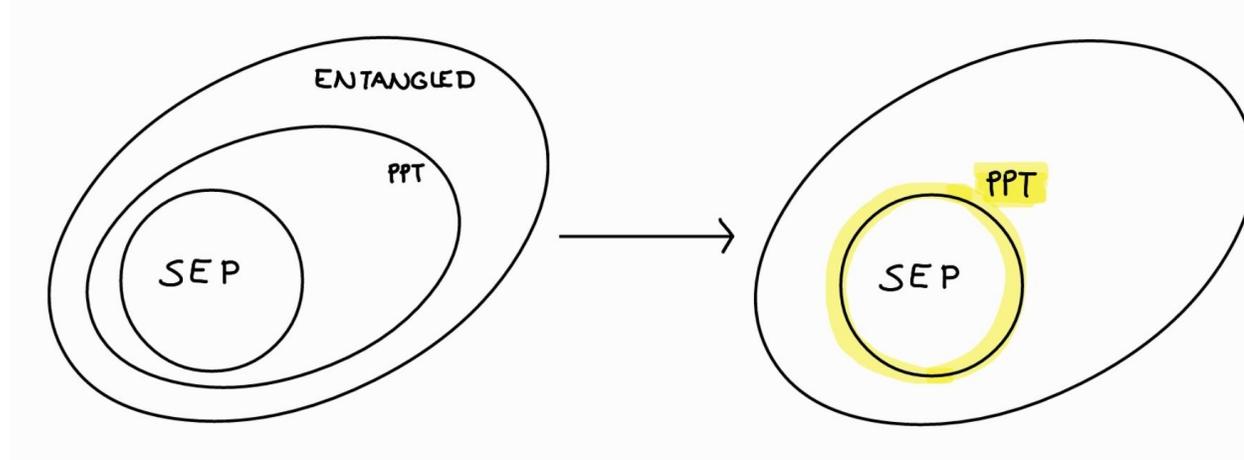
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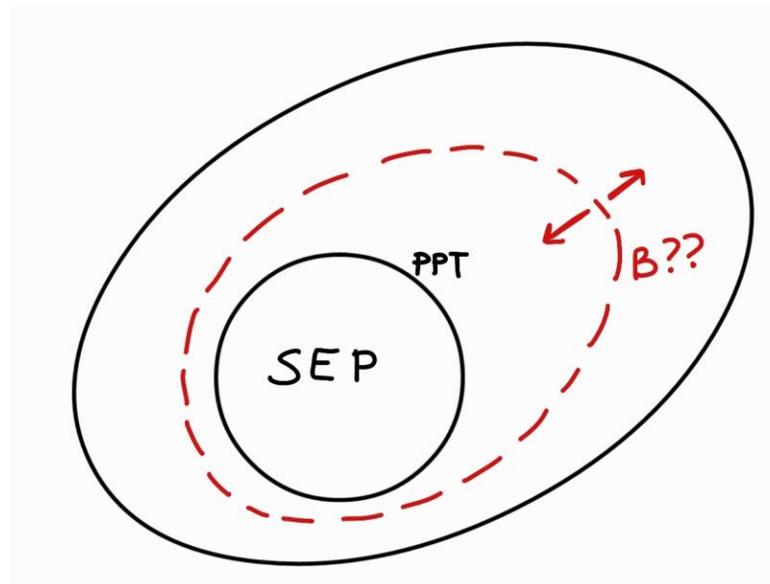
Faithfulness of our witness depends on the distance between B^{ent} and B^{sep}

3. RESULTS

For locally symmetric bipartite Gaussians, PPT is necessary and sufficient:



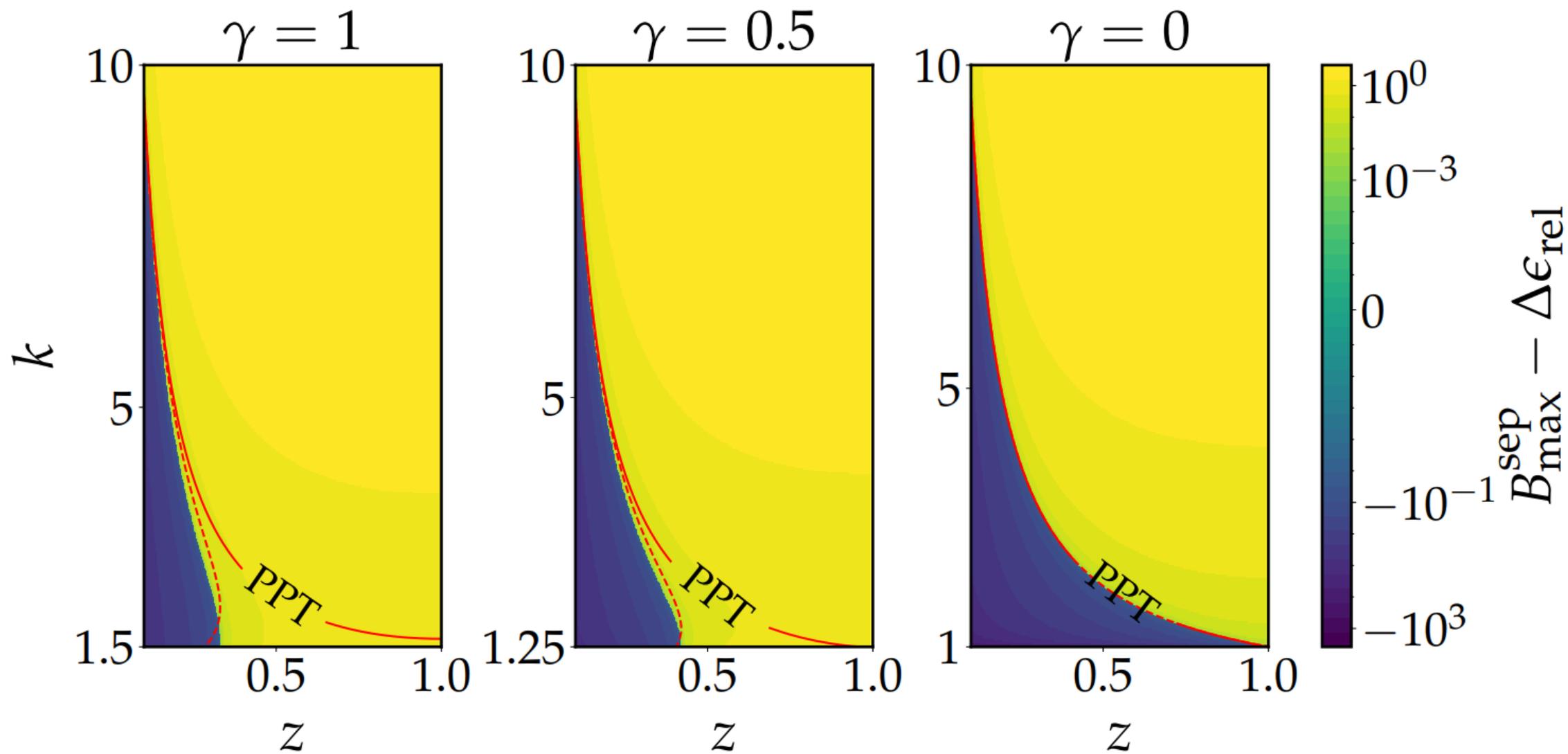
Question: how “good” is our criterion at detecting entangled states?



We study the parametric family of two-mode-squeezed states:

$$TMS(z, k, \gamma)$$

3. RESULTS

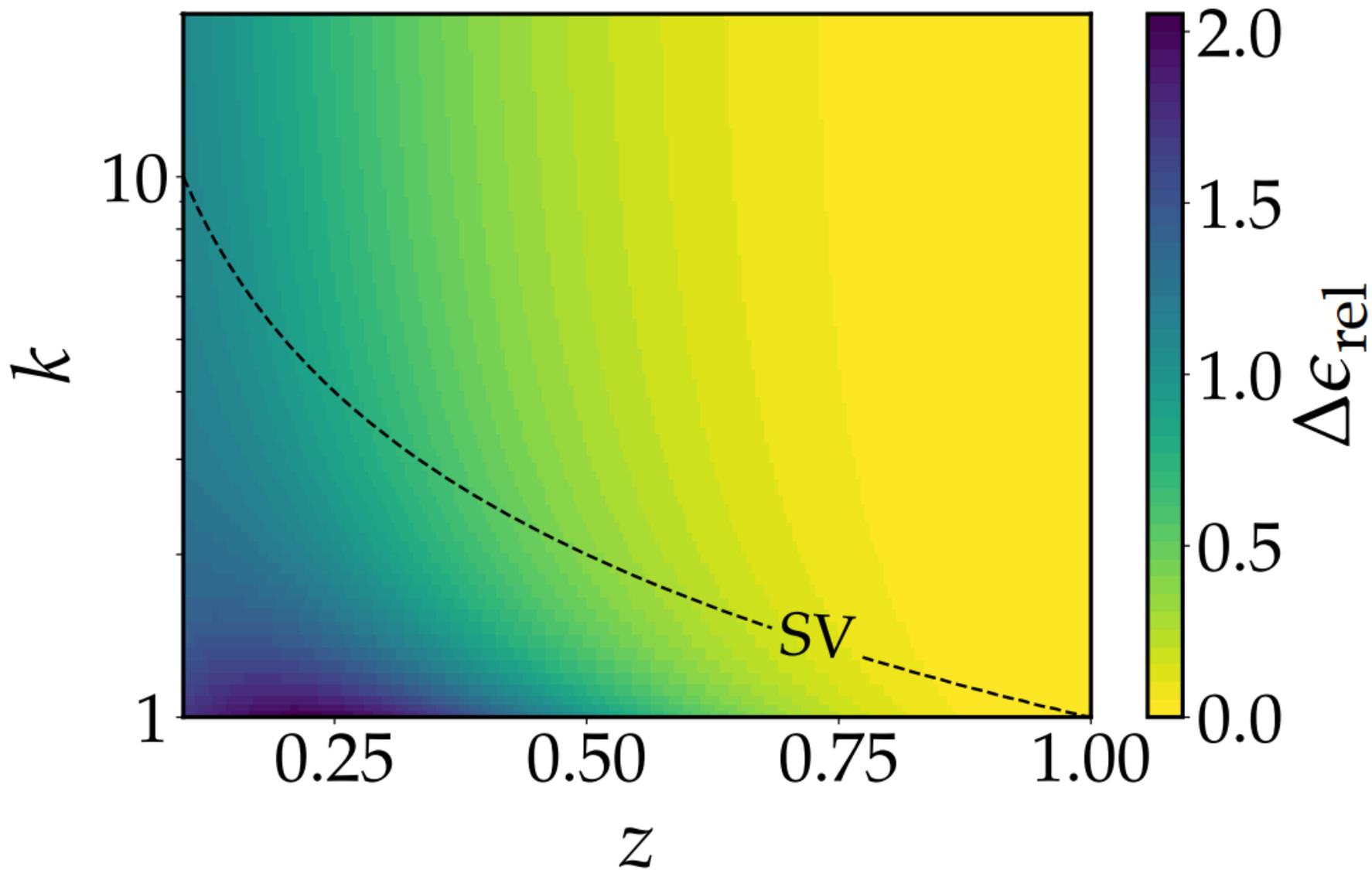


Non-Gaussian case

- We study the behaviour of Gaussian relative ergotropic gap on non-Gaussian states
- Focus on TMS states (Gaussian) that undergo a photon subtraction (non-Gaussian) in one of the modes
- Apply SV criterion as information-theoretic witness of entanglement

$$\langle a^\dagger a \rangle_\rho \langle b^\dagger b \rangle_\rho - \langle ab \rangle_\rho \langle a^\dagger b^\dagger \rangle_\rho < 0 \implies \rho \text{ entangled}$$

Non-Gaussian case



4. CONCLUSIONS and OUTLOOK

- Relative ergotropic gap as a witness of entanglement for Gaussian mixed bipartite states (locally symmetric)
- Independent quantity from mutual information
- Bound on the maximum gap for two-mode Gaussian separable states
- Bound on the minimum gap for two-mode Gaussian entangled states
- Necessary and sufficient criterion for states with symmetric thermal fluctuations (equivalent to PPT)
- Possible extension of the applicability of the criterion to more complex non-Gaussian states

4. CONCLUSIONS and OUTLOOK

- Generalization to broader classes of non-Gaussian states
- Multipartite scenario
- Efficiency benchmark ($\#$ copies) with respect to quantum tomography

BACK-UP SLIDES

Gaussian relative ergotropic gap:

$$\Delta\mathcal{E}_{rel} = \frac{1}{(k-1)(1+\alpha) + \gamma(1-\alpha)} \cdot \left[\sqrt{(k+\gamma)^2 \cos^4\theta + (k-\gamma)^2 \sin^4\theta + (k^2 - \gamma^2) \cos^2\theta \sin^2\theta \left(\frac{z_1^2 + z_2^2}{z_1 z_2} \right)} \right. \\ \left. + \alpha \sqrt{(k-\gamma)^2 \cos^4\theta + (k+\gamma)^2 \sin^4\theta + (k^2 - \gamma^2) \cos^2\theta \sin^2\theta \left(\frac{z_1^2 + z_2^2}{z_1 z_2} \right)} - [k(1+\alpha) + \gamma(1-\alpha)] \right]$$

Two-mode Gaussian separability condition:

$$(k^4 + \gamma^4 - 2k^2\gamma^2 - 2k^2 - 2\gamma^2 + 1)z_1z_2 \geq 4\sin^2\theta\cos^2[(z_1^2 + z_2^2)(k^2 - \gamma^2) - z_1z_2(2k^2 + 2\gamma^2)]$$

Bound for separable and entangled states:

$$B^{\text{sep}} = \frac{\frac{1+\alpha}{2} \sqrt{1 + k^4 + \gamma^4 + 2k^2 + 2\gamma^2 - 2k^2\gamma^2 + 8k\gamma} - [k(1 + \alpha) + \gamma(1 - \alpha)]}{(k - 1)(1 + \alpha) + \gamma(1 - \alpha)}$$

$$B^{\text{ent}} = \frac{\frac{1+\alpha}{2} \sqrt{1 + k^4 + \gamma^4 + 2k^2 + 2\gamma^2 - 2k^2\gamma^2 - 8k\gamma} - [k(1 + \alpha) + \gamma(1 - \alpha)]}{(k - 1)(1 + \alpha) + \gamma(1 - \alpha)}$$

Distinction between DV and CV:

In continuous-variable systems,

$$\Delta\mathcal{E} = k \cdot (\text{correlations}) \propto k$$