

Lorenzo Paoloni
June 27th, 2024

On the Moduli Space Curvature at Infinity

*based on 2311.07979 with Luca Melotti & Fernando Marchesano
and WIP with Alberto Castellano & Fernando Marchesano*





Motivation: Swampland



Motivation: Swampland Conjectures



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Important for today's talk:



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- ❖ There will always exist trajectories of **infinite geodesic length** in the moduli space

Ooguri & Vafa '06



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- ❖ The scalar curvature of the moduli space near points at infinity is **non-positive** (strictly negative for a moduli space of dimension $d > 1$)



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Ooguri & Vafa '06

**COUNTEREXAMPLE:
POSITIVE DIVERGING CURVATURE**

type IIA on (a specific) CY 3-fold

Trenner & Wilson '09

Motivation: Swampland Conjectures

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- ❖ The scalar curvature of the moduli space near points at infinity is **negative** (strictly negative for a moduli space of dimension $d > 1$)

WHY?

Ooguri & Vafa '06

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Setup: type IIA on a Calabi-Yau



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Action for the bosonic part of the vector multiplets:

$$S_{4d}^{\text{VM}} = \frac{1}{2\kappa_4^2} \int_{\mathbb{R}^{1,3}} R * 1 - 2g_{ab} dT^a \wedge *d\bar{T}^{\bar{b}} + \frac{1}{2} \int_{\mathbb{R}^{1,3}} I_{AB} F^A \wedge *_4 F^B$$



Setup: Metric

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$$g_{ab} \stackrel{\text{LV}}{=} -\frac{\partial}{\partial T^a} \frac{\partial}{\partial \bar{T}^{\bar{b}}} \log \left(\frac{4}{3} \mathcal{K} \right)$$

Special Kähler manifold
of the **local** type

$$I_{AB} \stackrel{\text{LV}}{=} -\frac{\mathcal{K}}{6} \begin{pmatrix} 1 + 4g_{ab} b^a b^b & 4g_{ab} b^b \\ 4g_{ab} b^b & 4g_{ab} \end{pmatrix}$$

$$A = 0, a$$



Setup: EFT String Limits

Lanza et al '21

Class of infinite distance trajectories such that

$$t^a = t_0^a + e^a \phi, \quad \text{with} \quad \phi \rightarrow \infty$$

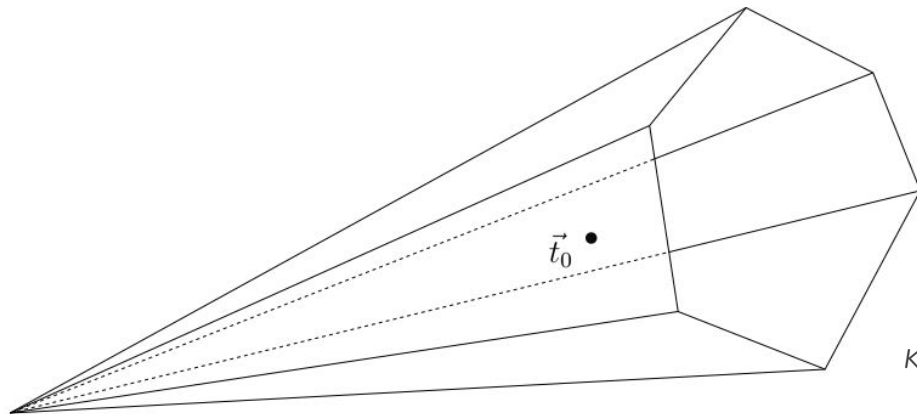


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Kähler cone



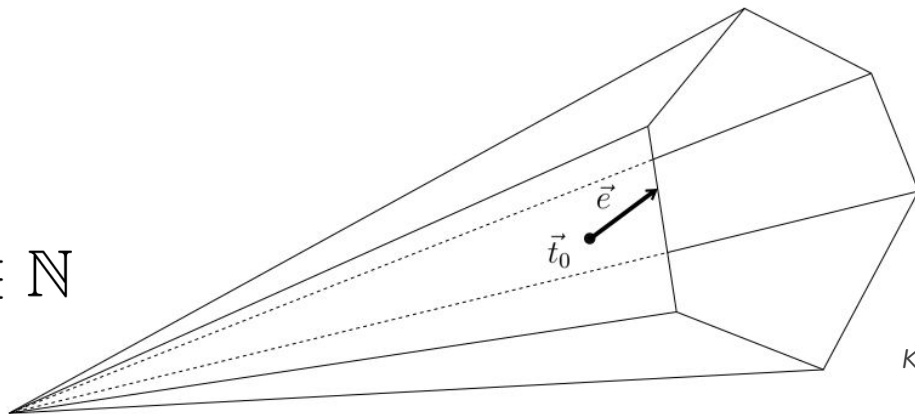
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Lanza et al '21

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$$e^a \in \mathbb{N}$$



Kähler cone



Setup: EFT String Limits

Lanza et al '21

Class of infinite distance trajectories such that

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In order not to move in the hypermultiplet moduli space, also

$$g_s(\phi) = g_{s,0} \frac{\mathcal{V}_{CY}^{1/2}(\phi)}{\mathcal{V}_{CY,0}^{1/2}} \rightarrow \infty$$



Scalar Curvature of the Moduli Space

Strominger '90

For a Special Kähler manifold the scalar curvature is

$$R^{\text{cl}} = -2n_V(n_V + 1) + \frac{9}{8\mathcal{K}^2} g^{ab} g^{cd} g^{ef} \mathcal{K}_{ace} \mathcal{K}_{bdf}$$



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Bounded from below but not from above



Origin of the Divergence



Origin of the Divergence

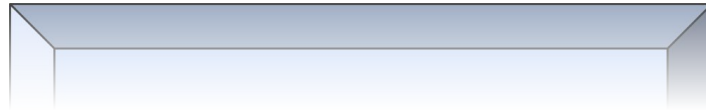
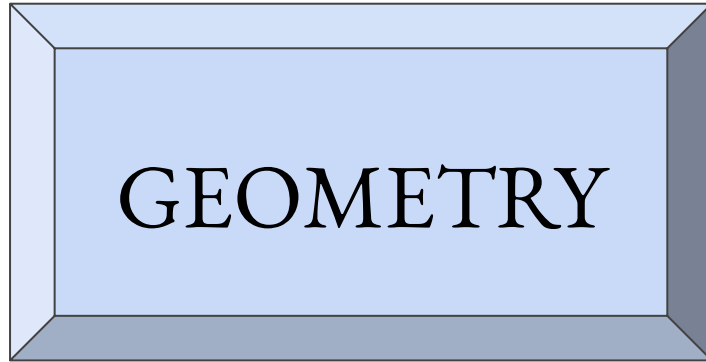


GEOMETRY



Origin of the Divergence

Luca Melotti's parallel session



- **M-th variables** perspective
- In terms of **boundaries** of the 5d M-th moduli space
- **Shrinking divisors**

Origin of the Divergence

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GEOMETRY



PHYSICS

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PHYSICS

- **4d EFT** perspective
- In terms of the **d.o.f.'s** that remain dynamical **below the cutoff**
- **Rigid theory**

Origin of the Divergence

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Origin of the Divergence: the EFT picture



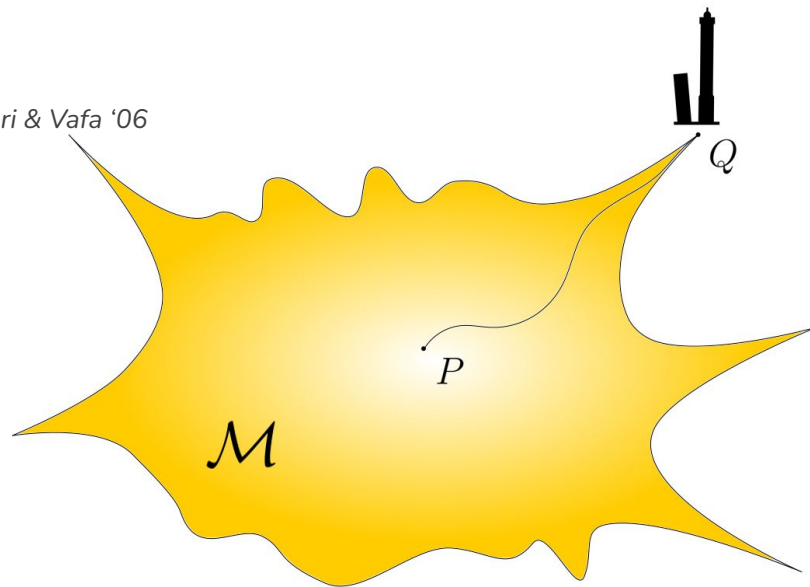
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Swampland Distance Conjecture

$$\frac{m_*(Q)}{M_P} \sim \frac{m_*(P)}{M_P} e^{-\alpha d(P,Q)}$$

$$d(P, Q) \longrightarrow \infty$$

Ooguri & Vafa '06



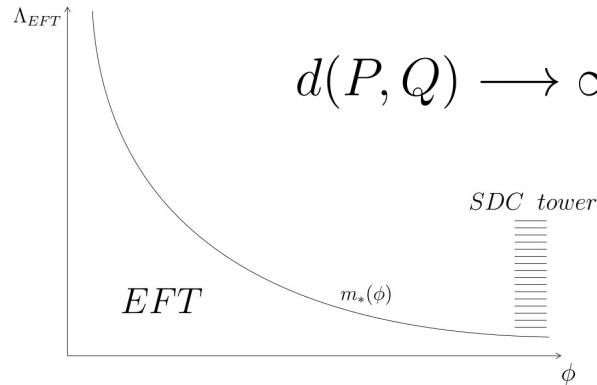
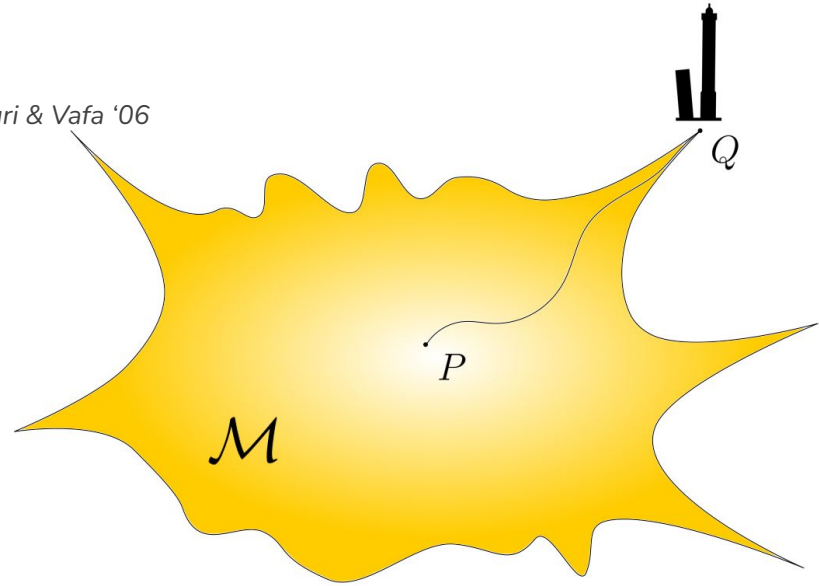
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$$\Lambda_{EFT} = m_*(\phi)$$



Origin of the Divergence: the EFT picture

For our limit

$$t^a \rightarrow \infty$$

$$g_s(\phi) \rightarrow \infty$$

the lightest tower is the one of D0-branes: $m_{D0} \sim g_s^{-1} \rightarrow 0$



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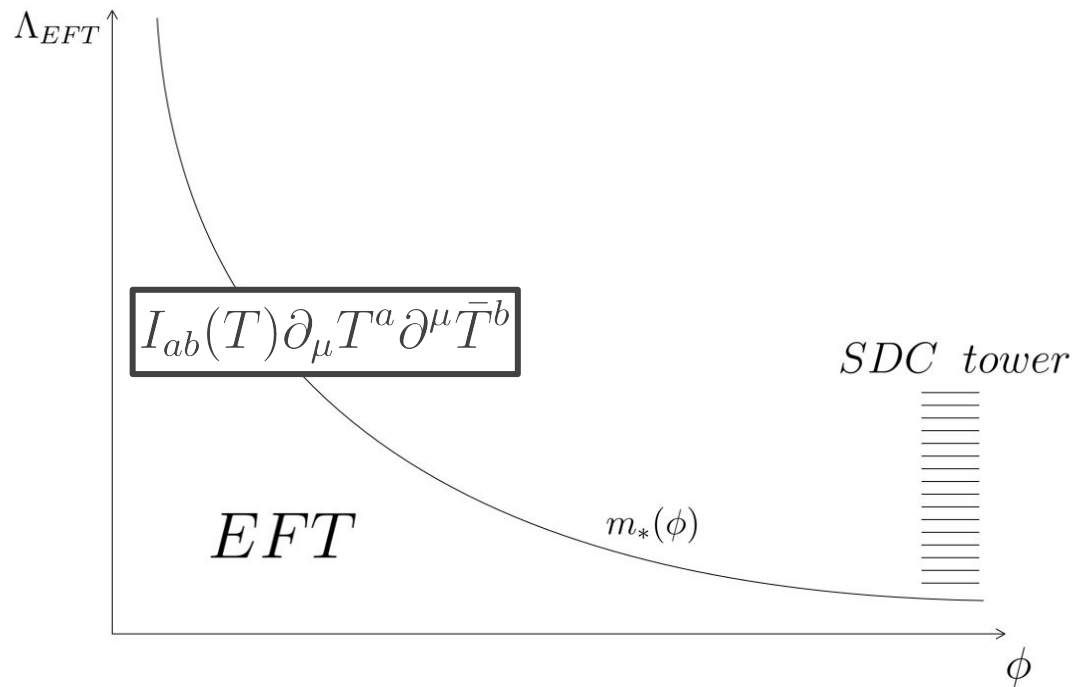


Origin of the Divergence: the EFT picture

$$\begin{aligned} S_{4d}^{\text{VM}} &\supset M_P^2 \int g_{ab} dT^a \wedge *d\bar{T}^{\bar{b}} \\ &= m_*^2 \int \tilde{g}_{ab} dT^a \wedge *d\bar{T}^{\bar{b}} \\ &\stackrel{!}{=} m_*^2 \int I_{ab} dT^a \wedge *d\bar{T}^{\bar{b}} \end{aligned}$$

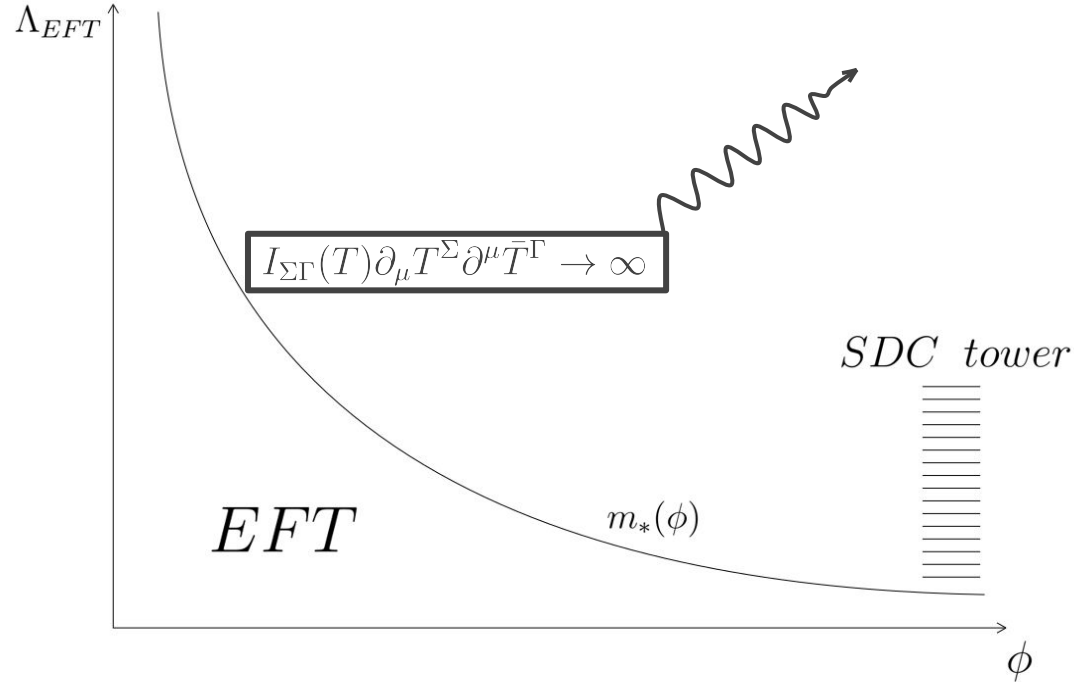
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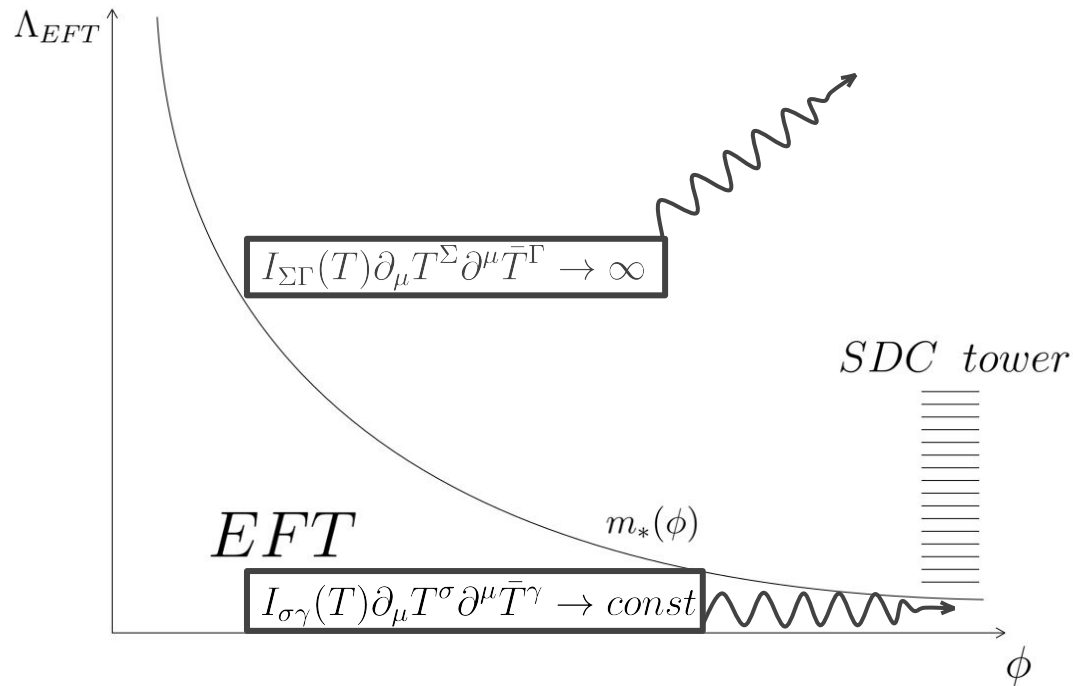
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Origin of the Divergence: the EFT picture

Below the SDC scale, we recover a 4d N=2 **rigid** field theory

$$S_{4d,rigid}^{VM} = m_*^2 \int_{\mathbb{R}^{1,3}} I_{\sigma\rho} dT^\sigma \wedge *d\bar{T}^{\bar{\rho}} + \frac{1}{2} \int_{\mathbb{R}^{1,3}} I_{\sigma\rho} F^\sigma \wedge *_4 F^\rho$$

Special Kähler manifold
of the **local** type

$$K \sim \log \mathcal{K}$$

Special Kähler manifold
of the **rigid** type

$$K \sim \mathcal{K}$$

How to select the directions:

$$\vec{t}_\sigma \in \ker \mathbf{K}$$

$$\mathbf{K}_{ab} = \mathcal{K}_{abc} e^c$$

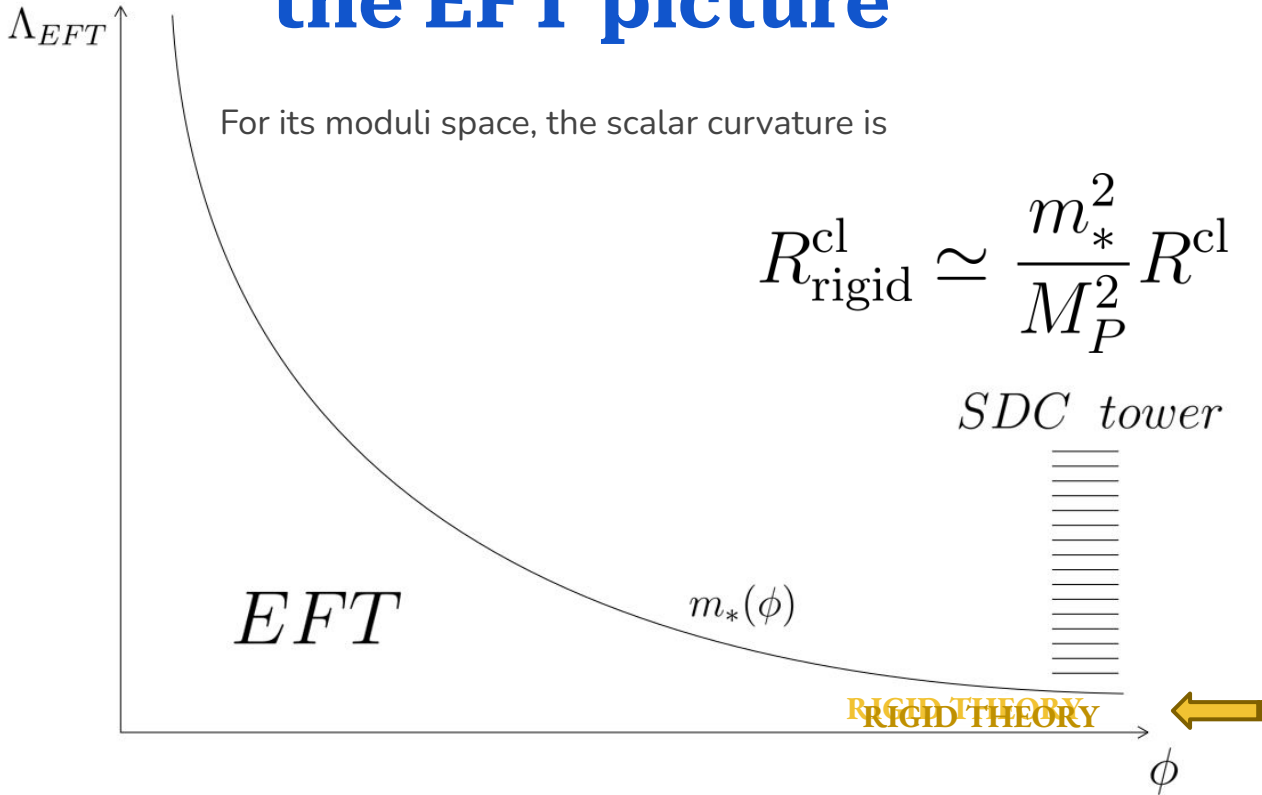


Origin of the Divergence: the EFT picture

For its moduli space, the scalar curvature is

$$R_{\text{rigid}}^{\text{cl}} \simeq \frac{m_*^2}{M_P^2} R^{\text{cl}}$$

Origin of the Divergence: the EFT picture



Curvature divergence
sourced by a gauge
theory that dominates
over gravity



The Curvature Criterion

Along a geodesic trajectory of infinite distance, moduli space scalar curvature that diverges asymptotically implies the presence of a field theory sector that is decoupled from gravity.



Conclusions

- ❖ We have analysed the asymptotic behaviour of the scalar curvature in **4d N=2 moduli spaces**, focusing on **type IIA CY VM sector** at **large volume**, which provide a huge set of limits, recently classified in light of the SDC.
- ❖ In our case, the **SDC tower always involved D0-branes**, and so there is an M-theory description.
- ❖ **Take-home message: curvature divergences** appear where there is a **non-trivial EFT below the SDC scale** that decouples from gravity.
- ❖ **Work in progress**: test this picture in **more general setups**, i.e. type IIB, conifold points, SW points, etc.



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Thank you!

Quantitative Analysis

Case	$R_{\text{IIA}}^{\text{cl}}(\phi \rightarrow \infty)$
$w=3$ — $r = n_V$	$-2n_V^2 + n_V + \mathfrak{e}$
$r < n_V$	$R_{\text{rigid}}^{\text{cl}} \frac{2}{3} \mathbf{k} \phi^3$
$w=2$ — $r = n_V$	$-2n_V^2 + n_V$
$r < n_V$, smooth	$-2(n_V^2 - 2n_V + 3)$
$r < n_V$, non-smooth	$[-2n_V^2 + 4n_V - 3r]^*$
$w=1$ — $r = n_V - 1$	$-2(n_V^2 - 2n_V + 3)$
$r < n_V - 1$	$R_{\text{rigid}}^{\text{cl}} 2\mathbf{K}_{\Sigma\Lambda} t_0^\Sigma t_0^\Lambda \phi$

$$\longrightarrow \mathfrak{e} = -\frac{\mathbf{k}}{6} \mathbf{K}^{ab} \mathbf{K}^{cd} \mathbf{K}^{ef} \mathcal{K}_{ace} \mathcal{K}_{bdf}$$

$$\longrightarrow \mathbf{k} = \mathcal{K}_{abc} e^a e^b e^c$$

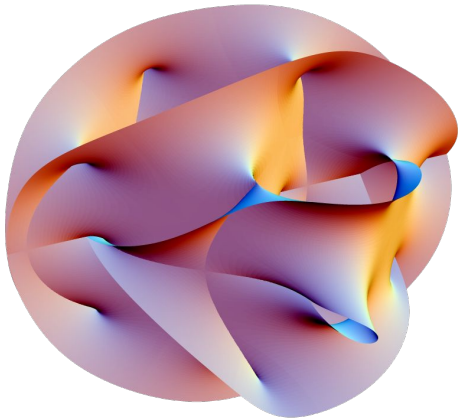
$\longrightarrow R_{\text{rigid}}^{\text{cl}} = 0$ but there can be divergence due to worldsheet instanton corrections

$$r = \text{rank}(\mathbf{K}) \quad \mathbf{K}_{ab} = \mathcal{K}_{abc} e^c$$

$$n_V = h^{1,1}(CY)$$

Origin of the Divergence: the Geometric picture

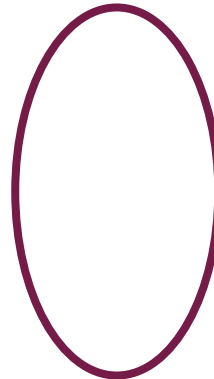
10d type IIA
on



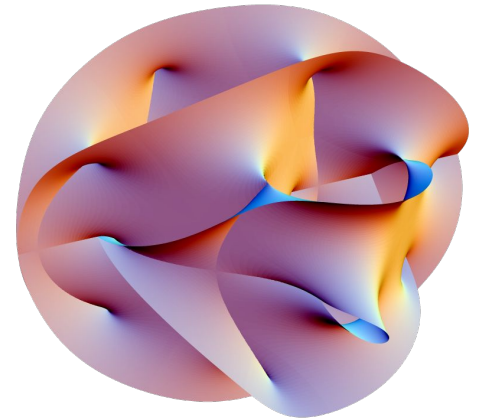
CY



11d M-theory
on



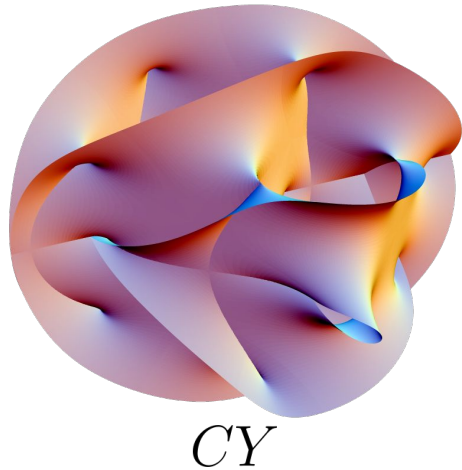
S^1



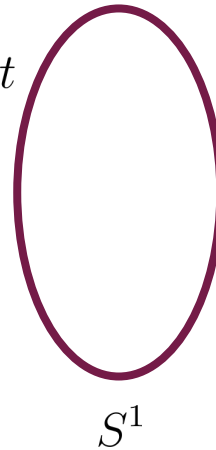
CY

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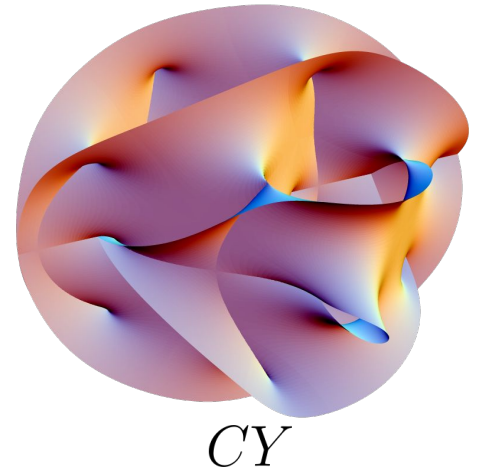
10d type IIA
on



$$\mathcal{V}_{11} = \frac{\mathcal{V}_{CY}}{g_s^2} \rightarrow \text{const}$$

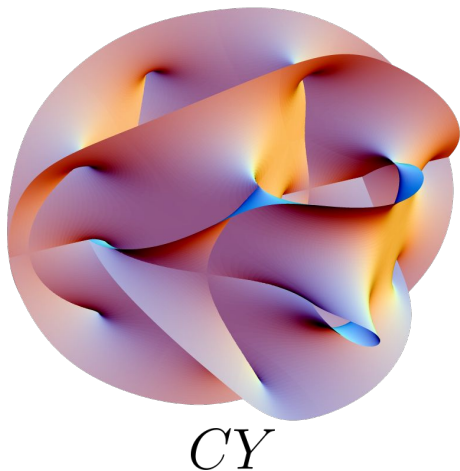


11d M-theory
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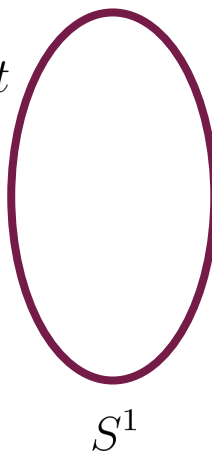
10d type IIA
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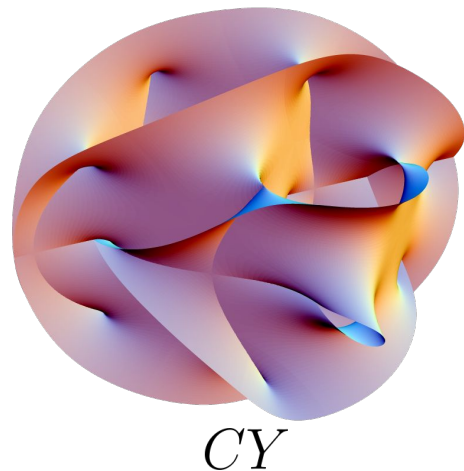
$$\mathcal{V}_{11} = \frac{\mathcal{V}_{CY}}{g_s^2} \rightarrow \text{const}$$



$$R_{11} = \frac{\mathcal{V}_{CY}^{\frac{1}{3}}}{\mathcal{V}_{11}^{\frac{1}{3}}} \rightarrow \infty$$

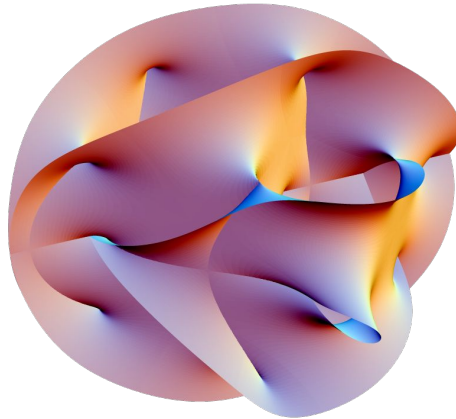


11d M-theory
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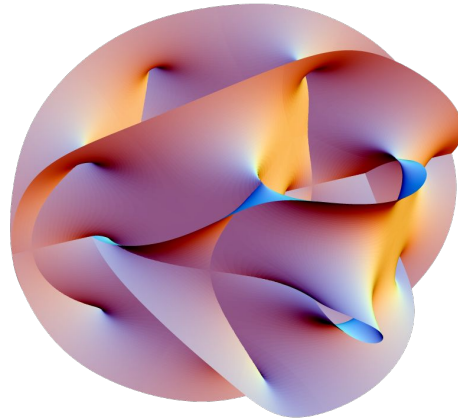
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5d $N=2$ SUGRA

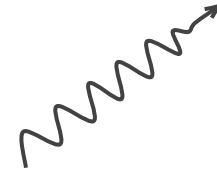
Origin of the Divergence: the Geometric picture

$$w = 3$$


11d M-theory
on



CY

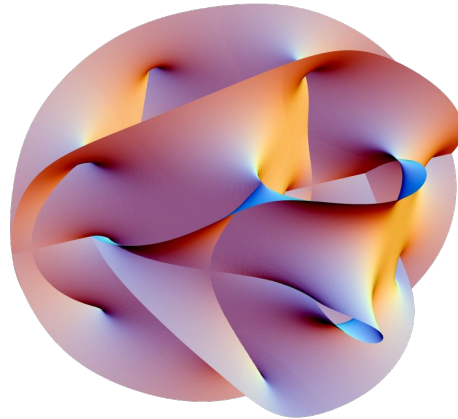


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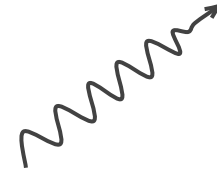
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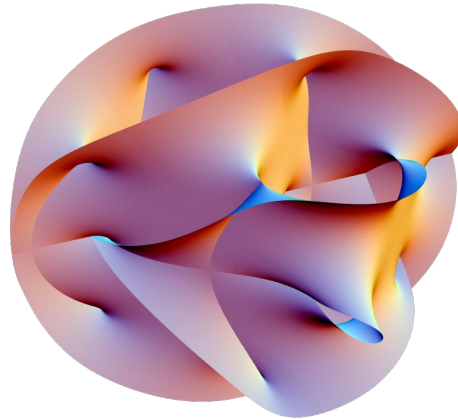
$$w = 2$$
$$w = 1$$


\equiv

$$5d \ N=2 \ \text{SUGRA}$$

Origin of the Divergence: the Geometric picture

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CY

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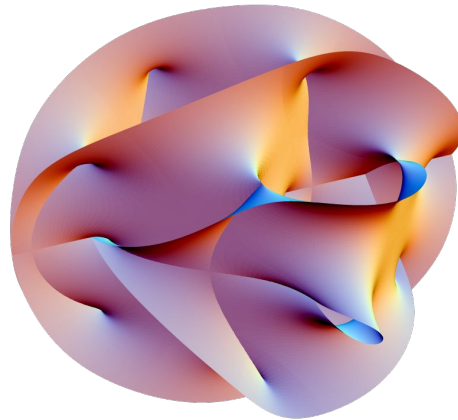
FEATURES:

➤ \mathcal{M}_{5d}^{VM}

➤ $M^a = \frac{t^a}{\mathcal{V}_{CY}^{\frac{1}{3}}}$

➤ $\mathcal{K}_{abc} M^a M^b M^c = 6$

11d M-theory
on



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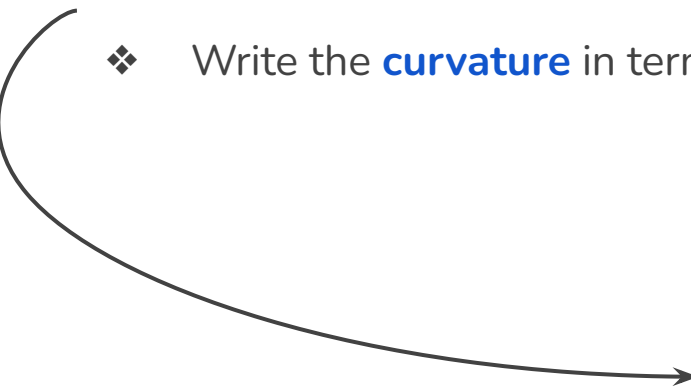
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5d $N=2$ SUGRA



Origin of the Divergence: the Geometric picture

- ❖ Map the **trajectory** of the limit in terms of the **5d variables**
- ❖ Write the **curvature** in terms of the **5d gauge kinetic function**



**THE CURVATURE CAN ONLY
DIVERGE AT THE BOUNDARIES OF
THE 5D MODULI SPACE**



Origin of the Divergence: the Geometric picture

Types of Calabi-Yau 3-fold (M-th) Kähler boundaries:

Witten '95

- **Finite distance boundaries** ($w=3$)

1. **Curve** collapsing to a **point**



NO DIVERGENCE

2. **Divisor** collapsing to a **curve**



NO DIVERGENCE

3. **Divisor** collapsing to a **point**



DIVERGENCE

- **Infinite distance boundaries** ($w=1,2$)



UNCERTAIN



Origin of the Divergence: the Geometric picture

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- **Finite distance boundaries** ($w=3$)
 1. **Curve** collapsing to a **point**
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$$\mathcal{D}_\sigma = t_\sigma^a \mathcal{D}_a$$
$$\vec{t}_\sigma \in \ker \mathbf{K}$$